# Rotational tree structures on binary trees and triangulations* 

Jean Marcel Pallo ${ }^{\dagger}$


#### Abstract

A rotation in a binary tree is a simple and local restructuring technique commonly used in computer science. We propose in this paper three restrictions on the general rotation operation. We study the case when only leftmost rotations are permitted, which corresponds to a natural flipping on polygon triangulations. The resulting combinatorial structure is a tree structure with the root as the greatest element. We exhibit an efficient algorithm for computing the join of two trees and the minimum number of leftmost rotations necessary to transform one tree into the other.


Keywords: Binary trees; Rotation; Distance; Lattice; Algorithms

## 1 Introduction

Rotation is one of the most common operations for restructuring binary trees. It has the advantage of altering the depths of some of the nodes in the tree while preserving the symmetric order of all the nodes. Thus rotation is commonly used in a variety of algorithms for maintaining binary search trees with a good amortized behavior [10, 24, 28].

The combinatorial properties of binary trees under the rotation operation have been studied for thirty years [27]. In [17] we have shown that a directed version of the rotation graph of binary trees with $n$ nodes is a lattice, known as the $n$th Tamari lattice. This corresponds to the case when only left rotations are permitted in the binary tree transformation. Over the last ten years, Tamari lattices have often been used as examples to illustrate algebraic theories [1, 3, 16, 25].

Initially, Tamari lattices were orderings of parenthesizations of words. But nowadays they can be described in other ways via the well-known bijections between families of Catalan combinatorial objects. A system that is isomorphic to Tamari lattices is that of triangulations of a convex polygon related by the diagonal flip operation. This is the transformation that converts one triangulation into another

[^0]

Figure 1: A triangulation diagonal flip and its corresponding binary tree rotation
by removing a diagonal in the triangulation and adding the diagonal that subdivides the resulting quadrilateral on the opposite way $[8,9,26]$ (see Fig. 1).

In 1982, Culik and Wood defined the rotation distance between two binary trees with the same number of leaves as the minimum number of rotations necessary to transform one tree into the other [4]. Using the classical bijection between binary trees with $n$ internal nodes and triangulations of $(n+2)$ - gons, the previous distance is equivalent to the minimum number of diagonal-flip transformations needed to convert one triangulation of a polygon into another. There remains today an open problem whether the rotation distance can be computed in polynomial time.

Therefore it seems natural to consider special instances of rotation transformations in order to obtain simpler operations [12, 24]. In [2] the rotation operation is limited to the case where the leftmost subtree is constrained to be a leaf. In $[5,6$, $11,22]$ the authors only allow rotations at nodes along the right arm of a tree.

The current paper belongs to this appoach. We consider the problem by limiting the general rotation operation to the restricted version where only leftmost rotations on trees are allowed. We obtain a tree structure which is a join-semilattice with the root as the greatest element. An efficient algorithm computes the corresponding restricted rotation distance. This algorithm is constructive: it builds a sequence of leftmost rotations transforming one tree into the other.

Clearly, the restricted rotation distance defined above is bounded below by the usual rotation distance for which no efficient algorithm is known to compute it
exactly. However, this restricted rotation distance is a weak approximation of the usual rotation distance. A better approximation can be found in [21, 23]. This new metric can be considered as a way of measuring the difference in shape between two binary trees.

## 2 Definitions and terminology

Let us denote by $\bigcirc$ (respectively $\square$ ) internal nodes (respectively leaves) of a binary tree. Let $T_{L}$ (respectively $T_{R}$ ) denote the left (respectively right) subtree of a binary tree $T$ (the order is significant). Thus we can write $T=\bigcirc T_{L} T_{R}$ in Polish notation, i.e. by traversing $T$ in preorder (visit the root and then the left and right subtrees recursively). The weight $|T|$ of a binary tree $T$ is the number of leaves of $T$. Let $B_{n}$ denote the set of binary trees with $n$ internal nodes (and thus with $n+1$ leaves). The leaves of $T \in B_{n}$ are numbered from 1 to $n+1$ by a preorder traversal of $T$ (i.e. from left to right). The left (respectively right) arm of $T \in B_{n}$ is the path from the root of $T$ to its first (respectively $(n+1)$ th) leaf. The mirror image $\widetilde{T}$ of $T$ is recursively defined by $\widetilde{T}=\bigcirc \widetilde{T_{R}} \widetilde{T_{L}}$ and $\widetilde{\square}=\square$. Let us define $\mathbf{0}_{n}=(\bigcirc \square)^{n} \square$ (respectively $\mathbf{1}_{n}=\bigcirc^{n} \square^{n+1}$ ) the tree of $B_{n}$ where every internal node has a leaf as a left (respectively right) child.

In this paper we use the representation of binary trees via weight sequences introduced in [17]. This coding is defined as follows. Given $T \in B_{n}$, the weight sequence of $T$ is the integer sequence $w_{T}=\left(w_{T}(1), \ldots, w_{T}(n)\right)$ where $w_{T}(i)$ is the weight of the largest subtree of $T$ whose last leaf is the $i$ th leaf (see Fig. 2). The usual left-rotation $\rightarrow$ on $B_{n}$ is defined as follows. A tree $T \in B_{n}$ being given, it associates a tree $T^{\prime}$ obtained by replacing some subtree $\bigcirc T_{1} \bigcirc T_{2} T_{3}$ of $T$ by the


Figure 2: Three lefmost left-rotations in $B_{4}$ and the corresponding flips in $T_{6}$
subtree $\bigcirc \bigcirc T_{1} T_{2} T_{3}$. Let $\xrightarrow{-1}$ denote the right-rotation and let $\xrightarrow{*}$ denote the reflexive transitive closure of $\rightarrow$. The usual rotation distance between $T$ and $T^{\prime} \in B_{n}$ is the fewest number of left- and right-rotations required to convert $T$ into $T^{\prime}$. We have proved in [17] the following characterization: given $T, T^{\prime} \in B_{n}$, we have $T \xrightarrow{*} T^{\prime}$ iff for all $i \in[1, n]: w_{T}(i) \leq w_{T^{\prime}}(i)$.

Let us consider $(n+2)$-gons, i.e. convex polygons with $n+2$ sides and with a distinguished side as the top. We label the other sides from 1 to $n+1$ counterclockwise. Any triangulation of the $(n+2)$-gon has $n$ triangles and $n-1$ non-crossing diagonals. Let $T_{n+2}$ denote the set of triangulations of the $(n+2)$-gon. There is an explicit bijection $\tau$ between $B_{n}$ and $T_{n+2}[23,26]$. The top of the $(n+2)$-gon $\tau(T)$ corresponds to the root of the tree $T$. The $i$ th side of $\tau(T)$ corresponds to the $i$ th leaf of $T$. Diagonals corresponds to internal nodes recursively as follows. If $j$ is the last leaf of the left subtree $T_{L}$ of $T$, then $T_{L}$ corresponds to the $(j+1)$-gon having edge set $\{1, \ldots, j\}$ and the right subtree $T_{R}$ corresponds to the $(n-j+2)$-gon having edge set $\{j+1, \ldots, n+1\}$ (see Fig. 1 and 2 ).

Given some $T \in B_{n}$ with $T \neq \mathbf{1}_{n}$, according to the Polish notation of $T$, consider the leftmost $\square$ followed by a $\bigcirc$ which respectively are the last leaf of a subtree $T_{1}$ and the root of a subtree $\bigcirc T_{2} T_{3}$. Thus the root of $\bigcirc T_{1} \bigcirc T_{2} T_{3}$ is located on the left arm of $T$. Then define as the leftmost left-rotation on $B_{n}$ the transformation $T \leadsto T^{\prime}$ which consists in converting the leftmost subtree $\bigcirc T_{1} \bigcirc T_{2} T_{3}$ of $T$ into $\bigcirc T_{1} T_{2} T_{3}$ (see Fig. 2). Given $T \in B_{n}$, the leftmost left-rotation transformation is uniquely defined.

Let us describe the transformation on $\tau(T) \in T_{n+2}$ which corresponds to the leftmost left-rotation on $T \in B_{n}$ via the classical bijection $\tau$ between $B_{n}$ and $T_{n+2}$. This transformation is the unique operation on $\tau(T)$ which consists in removing some diagonal and adding a new diagonal an end of which coincides with the vertex located between the root side and the side labelled 1 (see Fig. 2 and 3). This alternative formulation may seem more natural and intuitive. But the weight sequences of binary trees are more appropriate for calculations.

Let $\stackrel{*}{\sim}$ denote the reflexive transitive closure of $\leadsto$. The leftmost rotation graph $L G_{n}$ is the directed graph which has a node for each tree of $B_{n}$. Two nodes are adjacent when their corresponding trees differ by a single leftmost left-rotation. Since the leftmost left-rotation operation on $T$ is uniquely defined, $L G_{n}$ enjoys a tree structure. The leftmost rotation distance $d\left(T, T^{\prime}\right)$ between $T$ and $T^{\prime} \in B_{n}$ is the length of the unique path between $T$ and $T^{\prime}$ in the directed graph $L G_{n} . L G_{n}$ is a subgraph of the graph $G_{n}$ according to the usual rotation. Algebraic properties of $G_{n}$ can be found in $[1,3,16,20,25,26]$.

## 3 Tree structure $B_{n}$

Given $T \in B_{n}$ with $T \neq \mathbf{1}_{n}$ and $w_{T}$, we obtain the weight sequence of the unique $T^{\prime}$ such that $T \leadsto T^{\prime}$ in the following way. Let $i \geq 2$ be the smallest integer such that $w_{T}(i)=1$. Let $j=\max \left\{m \in[i, n] \mid i=m-w_{T}(m)+1\right\}$, i.e. the greatest integer $m$ such that the largest subtree with last leaf $m$ has $i$ as the first leaf. Then


Figure 3: The flipping tree structure $T_{6}$
$w_{T^{\prime}}=w_{T}$ except for the integer $j: w_{T^{\prime}}(j)=j$. It is worth noting that this integer $j$ cannot be modified further since we have $1 \leq w_{T}(k) \leq k$ for all $T \in B_{n}$ and $k \in[1, n]$.

The poset $\left(B_{n}, \stackrel{*}{\sim}\right)$ enjoys some properties which can be easily obtained. $\left(B_{n}, \stackrel{*}{\sim}\right.$ $)$ is a poset with greatest element $\mathbf{1}_{n}$ for which $w_{\mathbf{1}_{n}}=(1,2,3, \ldots, n)$. This poset has a tree structure (with the greatest element $\mathbf{1}_{n}$ as root) and thus is a join-semilattice (see Fig. 4 and 5 ). The poset $\left(B_{n}, \stackrel{*}{\sim}\right)$ is graded, i.e. there exists an integer-valued function $r$ defined on $B_{n}$ by $r(T)=\operatorname{card}\left\{i \in[1, n] \mid w_{T}(i)=i\right\}$ such that $T \stackrel{*}{\sim} T^{\prime}$ and $r\left(T^{\prime}\right)=1+r(T)$ iff $T \leadsto T^{\prime} . r(T)$ is equal to the number of internal nodes that are on the left arm of $T$. We have $r\left(\mathbf{1}_{n}\right)=n-1$.

Let us remark that $B_{n}$ is isomorphic to two subtrees of $B_{n+1}$. One is obtained by sustituting $\bigcirc \square \square$ for the last leaf $\square$ in all the $B_{n}$ trees. If $\left(w_{1}, \ldots, w_{n}\right) \in B_{n}$, then $\left(w_{1}, \ldots, w_{n}, 1\right)$ is the weight sequence of a tree in the corresponding subtree of $B_{n+1}$. The other is obtained by sustituting $\bigcirc \square \square$ for the one before last leaf $\square$ in all the $B_{n}$ trees. If $\left(w_{1}, \ldots, w_{n}\right) \in B_{n}$, then $\left(w_{1}, \ldots, w_{n-1}, 1,1+w_{n}\right)$ is the weight sequence of a tree in the corresponding subtree of $B_{n+1}$. For example in Fig. 5, the left and right subtrees of $B_{5}$ are isomorphic to $B_{4}$ (Fig. 4).


Figure 4: The leftmost tree structure $B_{4}$


Figure 5: The leftmost tree structure $B_{5}$

The leftmost rotation distance between $T$ and $T^{\prime}$ can be computed by the formula $d\left(T, T^{\prime}\right)=2 r\left(T \vee T^{\prime}\right)-r(T)-r\left(T^{\prime}\right)$. Thus we are led to compute the join $T \vee T^{\prime}$ of any couple of trees $T$ and $T^{\prime}$.

## 4 Computing joins and leftmost rotation distance

We already have observed that in applying the leftmost rotation $T \sim T^{\prime}$ the unique integer which has been transformed reaches its maximal possible value and thus cannot increase. Now, for every $T \in B_{n}$, compute from $w_{T}$ an ordered array $a_{T}$ which keeps track of the sequence of all the integer transformations for designing the unique path between $T$ and $\mathbf{1}_{n}$.

```
Algorithm (Computation of \(a_{T}\) from \(w_{T}\) )
Given \(T \in B_{n}\) and its weight sequence \(w_{T}\)
\(k:=1\)
for \(i:=1\) to \(n\) do
    if \(w_{T}(i)=1\) then
        for \(j:=n\) downto \(i\) do
            if \(i=j-w_{T}(j)+1\) then \(a_{T}(k):=j ; k:=k+1\) endif
        enddo
    endif
enddo
```

This algorithm requires $O\left(n^{2}\right)$ time in the worst case and $O(n)$ space.
The join $T \vee T^{\prime}$ of $T$ and $T^{\prime}$ is located at the intersection of the two paths connecting $T$ and $T^{\prime}$ to $\mathbf{1}_{n}$. Thus we compute $w_{T \vee T^{\prime}}$ in the following way.

Let us consider the greatest suffix which is common to $a_{T}$ and $a_{T^{\prime}}$ (if it exists). The corresponding prefixes of $a_{T}$ and $a_{T^{\prime}}$ contain the same integers $i$ (possibly in different order) for which $w_{T \vee T^{\prime}}(i)=i$. The remaining integers $j$ verify $w_{T \vee T^{\prime}}(j)=$ $w_{T}(j)=w_{T^{\prime}}(j)$. Therefore it is easy to compute $w_{T \vee T^{\prime}}$, and then $r(T), r\left(T^{\prime}\right)$, $d\left(T, T^{\prime}\right)=2 r\left(T \vee T^{\prime}\right)-r(T)-r\left(T^{\prime}\right)$ using the rank function $r(T)=\operatorname{card\{ i} \in$ $\left.[1, n] \mid w_{T}(i)=i\right\}$. See some examples in Table 1 where suffixes are shown in bold type.

Table 1:

| $w_{T}$ | $w_{T^{\prime}}$ | $a_{T}$ | $a_{T^{\prime}}$ | $w_{T \vee T^{\prime}}$ | $d\left(T, T^{\prime}\right)$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 11112 | 11315 | 12354 | 53124 | 12315 | 4 |
| 11234 | 11345 | 15432 | 54312 | 11345 | 3 |
| 11214 | 11215 | 15324 | 51324 | 11215 | 1 |
| 11111 | 12345 | 12345 | 54321 | 12345 | 4 |
| 11111 | 11114 | 12345 | 15234 | 12345 | 8 |
| 11315 | 12112 | 53124 | 21354 | 12315 | 3 |
| 11212 | 11114 | 13254 | 15234 | 12315 | 6 |

$a_{T}$ (respectively $a_{T^{\prime}}$ ) allows to build the unique path between $T$ and $T \vee T^{\prime}$ (respectively $T^{\prime}$ and $\left.T \vee T^{\prime}\right)$. Thus we obtain the unique path $\left(T, T \vee T^{\prime}, T^{\prime}\right)$ between $T$ and $T^{\prime}$.

## 5 Mirror leftmost rotation distance

Let us define the mirror leftmost rotation $\hookrightarrow$ on $B_{n}$ by $T \hookrightarrow T^{\prime}$ iff $\widetilde{T^{\prime}} \leadsto \widetilde{T}$. Then $\left(B_{n}, \stackrel{*}{\hookrightarrow}\right)$ is a poset with least element $\mathbf{0}_{n}$ for which $w_{\mathbf{0}_{n}}=(1,1,1, \ldots, 1)$. This poset has a tree structure (with the least element $\mathbf{0}_{n}$ as root) and thus is a meet-
semilattice. This poset $\left(B_{n}, \stackrel{*}{\hookrightarrow}\right)$ is ranked by the rank function $\rho(T)=n-k_{T}+1$ where $k_{T}$ is the number of internal nodes on the right arm of $T \in B_{n}$. We have $\rho\left(\mathbf{0}_{n}\right)=1$ The following algorithm computes $\rho(T)$ using the weight sequence of $T$ :

## Rank algorithm (Computation of $\rho(T)$ from $w_{T}$ )

Given $T \in B_{n}$ and its weight sequence $w_{T}$;
$k_{T}:=1 ; i:=n$;
while $i>1$ do
if $w_{T}(i)=1$ then $k_{T}:=k_{T}+1 ; i:=i-1$
else $i:=i-w_{T}(i)+1$ endif
enddo
$\rho(T)=n-k_{T}+1$
See $\left(B_{4}, \stackrel{*}{\hookrightarrow}\right)$ in Fig. 6. Observe that $\hookrightarrow$ is a particular case of the right-arm rotation transformation defined in [22]. As illustration, compare for example Fig. 3 of [22, p. 176] and Fig. 6 of this paper. The edge which links 1112 and 1212 in Fig. 3 of [22] has disappeared in Fig. 6. The graph drawn in Fig. 3 of [22] does not enjoy the tree structure property.


Figure 6: The mirror image of $B_{4}$

Let us define the mirror leftmost rotation distance $\tilde{d}\left(T, T^{\prime}\right)$ between $T$ and $T^{\prime} \in B_{n}$ as the length of the unique path between $T$ and $T^{\prime}$ in the graph of $\left(B_{n}, \stackrel{*}{\hookrightarrow}\right)$. Therefore we have: $\widetilde{d}\left(T, T^{\prime}\right)=d\left(\widetilde{T}, \widetilde{T^{\prime}}\right)$.

Since $w_{\widetilde{T}}$ can be easily computed recursively from $w_{T}$, the mirror leftmost rotation distance $\widetilde{d}\left(T, T^{\prime}\right)=d\left(\widetilde{T}, \widetilde{T^{\prime}}\right)$ is computed using Section 4. Then $\delta\left(T, T^{\prime}\right)=$ $\min \left(d\left(T, T^{\prime}\right), d\left(\widetilde{T}, \widetilde{T^{\prime}}\right)\right)$ is bounded below by the usual rotation distance for which no polynomial time algorithm is known to compute it exactly today. See some examples in $B_{8}$ (Table 2).

Table 2:

| $w_{T}$ | $w_{T^{\prime}}$ | $d\left(T, T^{\prime}\right)$ | $w_{\widetilde{T}}$ | $w_{\widetilde{T^{\prime}}}$ | $d\left(\widetilde{T}, \widetilde{T^{\prime}}\right)$ | $\delta\left(T, T^{\prime}\right)$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 11121511 | 12123611 | 8 | 12312148 | 12311141 | 9 | 8 |
| 11121518 | 11234112 | 11 | 11212147 | 11341118 | 11 | 11 |
| 11312312 | 11214111 | 13 | 11311612 | 12341218 | 6 | 6 |
| 11115123 | 12311312 | 11 | 11141234 | 11312611 | 11 | 11 |
| 11111123 | 11231237 | 14 | 11145678 | 11114118 | 8 | 8 |
| 11235112 | 12115111 | 11 | 11341114 | 12341231 | 9 | 9 |
| 11211612 | 11111312 | 5 | 11312315 | 11312678 | 9 | 5 |
| 11311245 | 11341678 | 6 | 11113612 | 12112678 | 9 | 6 |

## 6 Open problems

We propose below two other new definitions of restricted rotations which lead to computing open problems.
First we can restrict the general definition of the rotation transformation by choosing $\bigcirc T_{1} \bigcirc T_{2} T_{3}$ as the rightmost subtree in the Polish notation of $T$. More precisely, let us consider in the Polish notation of $T$ the rightmost pattern $\square \bigcirc$ made up of a $\square$ followed by a $\bigcirc$. This $\bigcirc$ is the root of a subtree denoted by $\bigcirc T_{2} T_{3}$, and thus $T_{3}$ is always equal to a leaf $\square$. Let us denote by $T_{1}$ the largest subtree of $T$ whose last leaf is the leaf $\square$ involved in the previous pattern $\square \bigcirc$. The uniquely defined rotation which transforms $\bigcirc T_{1} \bigcirc T_{2} \square$ of $T$ into $\bigcirc \bigcirc T_{1} T_{2} \square$ is called rightmost left-rotation on the tree $T . B_{n}$ endowed with this transformation has a tree structure (with the root as the greatest element $\mathbf{1}_{n}$ ) and thus is a join-semilattice (see Fig. 7). Despite this tree structure, the direct computation of the joins of two trees seems to be more arduous. The definition of an efficient algorithm for computing the corresponding rightmost rotation distance $d^{\prime}$ seems difficult, too. However, we can easily exhibit the unique paths connecting $T$ and $T^{\prime}$ with $\mathbf{1}_{n}$. The weight sequence of the unique tree $\operatorname{succ}(T)$ obtained from $T$ by a rightmost rotation is such that $w_{\operatorname{succ}(T)}=w_{T}$ except for the integer $i=\max \left\{k \in[j, n] \mid w_{T}(k)=k-j+1\right\}$ where $j=\max \left\{l \in[1, n] \mid w_{T}(l)=1\right\}$. For this integer $i$, we have $w_{\operatorname{succ}(T)}(i)=w_{T}(i)+w_{T}\left(i-w_{T}(i)\right)$. The join $T \vee T^{\prime}$ of $T$ and $T^{\prime}$ is located at the intersection of the two paths $\left(T, \mathbf{1}_{n}\right)$ and $\left(T^{\prime}, \mathbf{1}_{n}\right)$. Unfortunately, this rough construction requires $O\left(n^{3}\right)$ time and $O\left(n^{2}\right)$ space.

It is worth noting that leftmost $d$ and rightmost $d^{\prime}$ rotation distances cannot be compared. For example: $d(1112,1114)=3<d^{\prime}(1112,1114)=4$ and $d^{\prime}(1113,1121)=2<d(1113,1121)=6$ (see Fig. 4 and 7$)$.

Second, we have limited in [2] the rotation operation to the case where the leftmost subtree $T_{1}$ of the subtree $\bigcirc T_{1} \bigcirc T_{2} T_{3}$ is always constrained to be a leaf $\square$. This transformation $\bigcirc \square \bigcirc T_{2} T_{3} \xrightarrow{L} \bigcirc \bigcirc \square T_{2} T_{3}$ induces a graded lower semimodular meet-semilattice structure on $B_{n}$. We can define a new restricted rotation by compelling, this time, the central subtree $T_{2}$ of the subtree $\bigcirc T_{1} \bigcirc T_{2} T_{3}$ to be always


Figure 7: The rightmost tree structure $B_{4}$


Figure 8: The central poset $B_{4}$
equal to a leaf $\square$. This transformation $\bigcirc T_{1} \bigcirc \square T_{3} \xrightarrow{C} \bigcirc \bigcirc T_{1} \square T_{3}$ induces a graded poset structure on $B_{n}$, but does not have as good algebraic properties as before. However, this "central" rotation operation $\xrightarrow{C}$ has a nice characterization: $T \xrightarrow{C} T^{\prime}$ iff $w_{T}=w_{T^{\prime}}$ except for an integer $i$ such that $w_{T}(i)=1<w_{T^{\prime}}(i)$ (see Fig. 8). The rank of $T \in B_{n}$ is easily computed by $r(T)=n+1-\operatorname{card}\left\{i \in[1, n] \mid w_{T}(i)=1\right\}$. Here too, it seems difficult to exhibit an efficient algorithm for computing the corresponding central rotation distance.

## Acknowledgement

I would like to thank the anonymous referees for their constructive remarks and recommendations which have greatly helped to improve this paper.

## References

[1] M.K. Bennet, G. Birkhoff, Two families of Newman lattices, Alg. Universalis 32(1994), 115-144.
[2] A. Bonnin, J. Pallo, A shortest path metric on unlabeled binary trees, Pattern Recognition Lett. 13(1992), 411-415.
[3] C. Chameni-Nembua, B. Monjardet, Les treillis pseudocomplments finis, European J. Combin. 13(1992), 89-107.
[4] K. Cukik, D. Wood, A note on some tree similarity measures, Inform. Process. Lett. 15(1982), 39-42.
[5] S. Cleary, Restricted rotation distance between binary trees, Inform. Process. Lett. 84(2002), 333-338.
[6] S. Cleary, J. Taback, Bounding restricted rotation distance, Inform. Process. Lett. 88(2003), 251-256.
[7] R.D. Dutton, R.O. Rogers, Properties of the rotation graph of binary trees, Congr. Numer. 109(1995), 51-63.
[8] S. Hanke, T. Ottmann, S. Schuierer, The edge-flipping distance of triangulations, J. Universal Comput. Sci. 2(1996), 570-579.
[9] F. Hurtado, M. Noy, J. Urrutia, Flipping edges in triangulations, Discrete Comput. Geom. 22(1999), 333-346.
[10] K.S. Larsen, E. Soisalon-Soininen, P. Widmayer, Relaxed balance using standard rotations, Algorithmica 31(2001), 501-512.
[11] J.M. Lucas, A direct algorithm for restricted rotation distance, Inform. Process. Lett. 90(2004), 129-134.
[12] J.M. Lucas, Localized rotation distance in binary trees, Congr. Numer. 169 (2004), 161-178.
[13] J.M. Lucas, Untangling binary trees via rotations, Comput. J. 47(2004), 259269.
[14] F. Luccio, L. Pagli, On the upper bound of the rotation distance of binary trees, Inform. Process. Lett. 31(1989), 57-60.
[15] E. Mäkinen, On the rotation distance of binary trees, Inform. Process. Lett. 26(1987/88), 271-272.
[16] G. Markowski, Primes, irreducibles and extremal lattices, Order 9(1992), 265290.
[17] J.M. Pallo, Enumerating, ranking and unranking binary trees, Comput. J. 29(1986), 171-175.
[18] J.M. Pallo, On the rotation distance in the lattice of binary trees, Inform. Process. Lett. 25(1987), 369-373.
[19] J.M. Pallo, Some properties of the rotation lattice of binary trees, Comput. J. 31(1988), 564-565.
[20] J.M. Pallo, An algorithm to compute the Mbius function of the rotation lattice of binary trees, RAIRO Theoret. Inform. Appl. 27(1993), 341-348.
[21] J.M. Pallo, An efficient upper bound of the rotation distance of binary trees, Inform. Process. Lett. 73(2000), 87-92.
[22] J.M. Pallo, Right-arm rotation distance between binary trees, Inform. Process. Lett. 87(2003), 173-177.
[23] R.O. Rogers, On finding shortest paths in the rotation graph of binary trees, Congr. Numer. 137(1999), 75-95.
[24] A.A. Ruiz, F. Luccio, A.M. Enriquez, L. Pagli, $k$-restricted rotation with an application to search tree rebalancing, 9th WADS, Lecture Notes in Computer Science, Springer, vol. 3608(2005), 2-13.
[25] B.E. Sagan, A generalization of Rota's NBC theorem, Adv. Math. 111(1995), 195-207.
[26] D.D. Sleator, R.E. Tarjan, W. Thurston, Rotation distance, triangulations and hyperbolic geometry, J. Amer. Math. Soc. 1(1988), 647-681.
[27] D. Tamari, Monodes prordonns et chanes de Malcev, Bull. Soc. Math. France $\mathbf{8 2 ( 1 9 5 4 ) , ~ 5 3 - 9 6 . ~}$
[28] R. Wilber, Lower bounds for accessing binary search trees with rotations, SIAM J. Comput. 18(1989), 56-67.


[^0]:    ${ }^{*}$ The results reported in this paper were presented at the 11 th International Conference AFL 2005 (Automata and Formal Languages) held at Dobogókő, Hungary, May 17-20.
    ${ }^{\dagger}$ LE2I, UMR 5158, Université de Bourgogne, BP 47870, F21078 DIJON-Cedex, France, E-mail: pallo@u-bourgogne.fr

