

A note on invariant linear forms on von Neumann algebras

By I. KOVÁCS and J. SZÜCS in Szeged

1. Let \mathbf{A} be a von Neumann algebra ¹⁾ in a complex Hilbert space \mathfrak{H} . We shall denote by \mathbf{A}^+ (resp. \mathbf{A}_1) the positive portion (resp. the unit ball) of \mathbf{A} : $\mathbf{A}^+ = \{T \in \mathbf{A} : T \cong 0\}$ (resp. $\mathbf{A}_1 = \{T \in \mathbf{A} : \|T\| \leq 1\}$). If \mathcal{G} is a group of $*$ -automorphisms of \mathbf{A} , set $\mathbf{A}^{\mathcal{G}} = \{T \in \mathbf{A} : \theta(T) = T \text{ for each } \theta \in \mathcal{G}\}$. It is not hard to see that $\mathbf{A}^{\mathcal{G}}$ is a von Neumann subalgebra of \mathbf{A} . For a given pair \mathbf{A}, \mathcal{G} , we shall denote by $\mathcal{R}(\mathbf{A}, \mathcal{G})$ the space of all ultra-weakly continuous linear forms σ on \mathbf{A} which are invariant with respect to \mathcal{G} . ²⁾ $\mathcal{R}^r(\mathbf{A}, \mathcal{G})$ (resp. $\mathcal{R}^+(\mathbf{A}, \mathcal{G})$) will denote the set of all real (resp. positive) ³⁾ elements of $\mathcal{R}(\mathbf{A}, \mathcal{G})$.

Consider an arbitrary element σ of $\mathcal{R}(\mathbf{A}, \mathcal{G})$ and set $M = \text{l.u.b.}_{T \in \mathbf{A}_1^+} \sigma(T)$, where $\mathbf{A}_1^+ = \mathbf{A}_1 \cap \mathbf{A}^+$. According to [4], there exists a projection E in \mathbf{A}_1^+ such that $\sigma(E) = M$. In this note we intend first to prove that E can be chosen to be an element of $\mathbf{A}^{\mathcal{G}}$. Then we shall study some consequences of this fact. Let us formulate it in the form of a

Theorem. *Let σ be an arbitrary element of $\mathcal{R}(\mathbf{A}, \mathcal{G})$ and set $M = \text{l.u.b.}_{T \in \mathbf{A}_1^+} \sigma(T)$. Then there exists a projection F of $\mathbf{A}^{\mathcal{G}}$ such that $\sigma(F) = M$.*

Remark. If \mathcal{G} is abelian, the theorem is a consequence of the Kakutani—Markov fixed point theorem (cf. [2, V. 10. 6]). In case \mathbf{A} is G -finite ([3]), the support ⁴⁾ of $E^{\mathcal{G}}$ has the property required (cf. [4]).

¹⁾ For the theory of von Neumann algebras we refer the reader to [1].

²⁾ I. e. $\sigma(\theta(T)) = \sigma(T)$ for every $T \in \mathbf{A}$ and $\theta \in \mathcal{G}$.

³⁾ For any $\sigma \in \mathcal{R}(\mathbf{A}, \mathcal{G})$, put $\sigma^*(T) = \sigma(T^*)$. It is evident that $\sigma^* \in \mathcal{R}(\mathbf{A}, \mathcal{G})$. σ is said to be real (resp. positive) if $\sigma = \sigma^*$ (resp. $\sigma(T) \geq 0$ for $T \in \mathbf{A}^+$). Any $\sigma \in \mathcal{R}(\mathbf{A}, \mathcal{G})$ can be uniquely written in the form $\sigma = \sigma_1 + i\sigma_2$ with $\sigma_1, \sigma_2 \in \mathcal{R}^r(\mathbf{A}, \mathcal{G})$. In fact, $\sigma_1 = \frac{1}{2}(\sigma + \sigma^*)$ and $\sigma_2 = \frac{1}{2i}(\sigma - \sigma^*)$.

In the following we prefer to use the notations: $\sigma_1 = \text{Re } \sigma$, $\sigma_2 = \text{Im } \sigma$.

⁴⁾ Cf. [1, App. III].

Proof of the theorem. Actually, the proof is based upon the following simple fact: Let T_1, \dots, T_n ($n=1, 2, \dots$) be elements in A^+ with supports E_1, \dots, E_n , respectively. Then the support E of $T = T_1 + \dots + T_n$ is equal to $\text{l.u.b.}_{1 \leq i \leq n} E_i$.

It is enough to show this statement for $n=2$, since then an induction argument will take care of the general case. For $n=2$ we prove that $I - E = (I - E_1) \cap (I - E_2)$ ⁵⁾ which evidently implies the assertion. Now the inequality $(I - E_1) \cap (I - E_2) \subseteq I - E$ is evident. To prove the converse of it, consider an arbitrary element x of $(I - E)\mathfrak{H}$. Then $Tx = (T_1 + T_2)x = 0$. Thus, $(T_1 + T_2)x|x = 0$ which gives that $(T_1x|x) = -(T_2x|x)$. As $T_1, T_2 \in A^+$, this is possible only if $(T_1x|x) = (T_2x|x) = 0$. But this implies that $T_1^{\frac{1}{2}}x = T_2^{\frac{1}{2}}x = 0$, i.e. $T_1x = T_2x = 0$. Hence $I - E \subseteq (I - E_1) \cap (I - E_2)$, which was to be proved. Now let $E \in A_1^+$ be a projection such that $\sigma(E) = M$ (cf. [4]), and consider an arbitrary finite system $\theta_1, \dots, \theta_n$ of elements of \mathcal{G} . Set $S_n = \frac{1}{n} \sum_{i=1}^n \theta_i(E)$. It is evident that $S_n \in A_1^+$ and $\sigma(S_n) = \frac{1}{n} \sum_{i=1}^n \sigma(\theta_i(E)) = \sigma(E) = M$. Since, for every i ($1 \leq i \leq n$), $\theta_i(E)$ is a projection, the support F_n of S_n is equal to $\text{l.u.b.}_{1 \leq i \leq n} \theta_i(E)$. Since $\sigma(S_n) = M$, we obtain that $\sigma(F_n) = M$, too (cf. [4]). Now if for each possible finite system J of elements of \mathcal{G} we take the corresponding projection F_J , we obtain an upward directed family $\{F_J\}_{J \subset \mathcal{G}}$ of projections. Put $F = \text{l.u.b.}_{J \subset \mathcal{G}} F_J$. F is a cluster point of the projections F_J in the strong operator topology (cf. [1, App. III]). Now taking into account the topological properties of the elements of \mathcal{G} and σ (cf. [1, chap. I. §§ 3—4]), for every $\theta_0 \in \mathcal{G}$ we have $\theta_0(F) = \theta_0(\text{l.u.b.}_{J \subset \mathcal{G}} F_J) = \text{l.u.b.}_{J \subset \mathcal{G}} \theta_0(F_J) = \text{l.u.b.}_{J \subset \mathcal{G}} \theta_0(F_J)$ ⁶⁾ $= F$, i.e. $F \in A^{\mathcal{G}}$, and $\sigma(F) = \text{l.u.b.}_{J \subset \mathcal{G}} \sigma(F_J)$. But, by construction, $\sigma(F_J) = M$ for each $J(\subset \mathcal{G})$, thus $\sigma(F) = M$, *q.e.d.*

2. Now let us present some consequences of this theorem.

Let σ_1 and σ_2 be two arbitrary elements of $\mathcal{R}(A, \mathcal{G})$ such that for every $T \in A^{\mathcal{G}}$ we have $\sigma_1(T) = \sigma_2(T)$. Put $\sigma = \sigma_1 - \sigma_2$, $\sigma' = \text{Re } \sigma$ and $\sigma'' = \text{Im } \sigma$. Since $\sigma'(T) = \sigma''(T) = 0$ for every $T \in A^{\mathcal{G}}$, by the preceding theorem we obtain that $\text{l.u.b.}_{S \in A_1^+} \sigma'(S) = \text{l.u.b.}_{S \in A_1^+} \sigma''(S) = 0$. Arguing with $-\sigma$ instead of σ , we can see that $\text{g.l.b.}_{S \in A_1^+} \sigma'(S) = \text{g.l.b.}_{S \in A_1^+} \sigma''(S) = 0$ as well. This means that $\sigma' = \sigma'' = 0$, i.e. $\sigma = 0$, hence $\sigma_1 = \sigma_2$.⁷⁾

Thus we obtain

⁵⁾ For two projections P and Q , $P \cap Q$ denotes the projection of \mathfrak{H} onto the subspace $(P\mathfrak{H}) \cap (Q\mathfrak{H})$.

⁶⁾ J' also runs over all possible finite systems of elements of \mathcal{G} .

⁷⁾ For $\sigma_1, \sigma_2 \in \mathcal{R}^+(A, \mathcal{G})$, this fact has been already established in [3].

Proposition 1. *Each element of $\mathcal{R}(\mathbf{A}, \mathcal{G})$ is uniquely determined by its restriction to $\mathbf{A}^{\mathcal{G}}$.*

Suppose now that σ belongs to $\mathcal{R}(\mathbf{A}, \mathcal{G})$, and denote by F the projection in $\mathbf{A}^{\mathcal{G}}$ such that $\sigma(F) = \text{l.u.b.}_{T \in \mathbf{A}^+} \sigma(T)$ (cf. Theorem). Put $\sigma_1(T) = \sigma(FT)$ and $\sigma_2(T) = -\sigma((I-F)T)$ ($T \in \mathbf{A}$). Then, according to [4], σ_1 and σ_2 are ultra-weakly continuous positive linear forms on \mathbf{A} with disjoint supports (cf. [1, chap. I, § 4, no. 6]) such that $\sigma = \sigma_1 - \sigma_2$. Moreover, it is evident that $\sigma_1, \sigma_2 \in \mathcal{R}^+(\mathbf{A}, \mathcal{G})$. Thus we have

Proposition 2. *Each element of $\mathcal{R}(\mathbf{A}, \mathcal{G})$ can be represented as a difference of two elements of $\mathcal{R}^+(\mathbf{A}, \mathcal{G})$ with disjoint supports. Therefore, each element of $\mathcal{R}(\mathbf{A}, \mathcal{G})$ is a finite linear combination of elements of $\mathcal{R}^+(\mathbf{A}, \mathcal{G})$. If $\mathbf{A}^{\mathcal{G}}$ reduces to the trivial von Neumann algebra of the scalars, then each element of $\mathcal{R}(\mathbf{A}, \mathcal{G})$ is either positive or negative (i.e. a positive linear form multiplied by -1).*

From this proposition we can conclude at once the following

Proposition 3. *\mathbf{A} is \mathcal{G} -finite if and only if for every $T \in \mathbf{A}^+, T \neq 0$, there exists an element σ of $\mathcal{R}(\mathbf{A}, \mathcal{G})$ such that $\sigma(T) \neq 0$.*

In particular if \mathcal{G} is the group of all inner automorphisms of \mathbf{A} , then $\mathcal{R}(\mathbf{A}, \mathcal{G})$ is identical with the space of all ultra-weakly continuous central (cf. [1, p. 275]) linear forms on \mathbf{A} . In this case Propositions 2 and 3 assert that

(i) *Each ultra-weakly continuous central linear form on \mathbf{A} is a linear combination of finite normal traces (cf. [1, chap. I, § 6, def. 1]). In particular if \mathbf{A} is a factor, and $\sigma \neq 0$ is an ultra-weakly continuous central linear form on \mathbf{A} , then \mathbf{A} is finite and σ is a scalar multiple of the canonical trace of \mathbf{A} . Furthermore if \mathbf{A} is a properly infinite von Neumann algebra (cf. [1, chap. I, § 6, def. 5]) then there exists no non-zero ultra-weakly continuous central linear form on \mathbf{A} .*

(ii) *\mathbf{A} is finite if and only if for every $T \in \mathbf{A}^+, T \neq 0$ there exists an ultra-weakly continuous central linear form σ on \mathbf{A} such that $\sigma(T) \neq 0$.*

Bibliography

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