# Existence of Positive Solutions for Boundary Value Problems of Second-order Functional Differential Equations 

Daqing Jiang<br>Northeast Normal University<br>Changchun 130024, China<br>Peixuan Weng ${ }^{1}$<br>South China Normal University<br>Guangzhou 510631, China


#### Abstract

We use a fixed point index theorem in cones to study the existence of positive solutions for boundary value problems of second-order functional differential equations of the form $$
\begin{cases}y^{\prime \prime}(x)+r(x) f(y(w(x)))=0, & 0<x<1 \\ \alpha y(x)-\beta y^{\prime}(x)=\xi(x), & a \leq x \leq 0 \\ \gamma y(x)+\delta y^{\prime}(x)=\eta(x), & 1 \leq x \leq b\end{cases}
$$ where $w(x)$ is a continuous function defined on $[0,1]$ and $r(x)$ is allowed to have singularities on $[0,1]$. The result here is the generalization of a corresponding result for ordinary differential equations.


Keywords: functional differential equation, boundary value problem, positive solution, superlinear and sublinear

1991 AMS classification: 34K10, 34B15

## 1 Introduction

Boundary value problems (abbr. as BVP) associated with second order diffferential equations have a long history and many different methods and techniques have been used and developed in order to obtain various qualitative properties of the solutions (see $[1-5,8,11,15,17]$ ). In recent years, accompanied by the development of theory of functional differential equations (abbr. as FDE), many authors have paid attention to BVP of second order FDE such as

$$
\left[p(t) x^{\prime}(t)\right]^{\prime}=f\left(t, x_{t}, x(t)\right)
$$

or

$$
x^{\prime \prime}(t)=f\left(t, x(t), x(\sigma(t)), x^{\prime}(t), x^{\prime}(\tau(t))\right)
$$

(for example see $[6-7,10,12-14,16]$ ). As pointed out by the authors of [6], the background for these problems lies in many areas of physics, applied mathematics and variational problems of control theory.

[^0]In this paper, we investigate the existence of positive solutions for BVP of secondorder FDE with the form:

$$
\begin{cases}y^{\prime \prime}(x)+r(x) f(y(w(x)))=0, & 0<x<1  \tag{1.1}\\ \alpha y(x)-\beta y^{\prime}(x)=\xi(x), & a \leq x \leq 0 \\ \gamma y(x)+\delta y^{\prime}(x)=\eta(x), & 1 \leq x \leq b\end{cases}
$$

Here we assume that
$\left(P_{1}\right) w(x)$ is a continuous function defined on $[0,1]$ satisfying

$$
c=\inf \{w(x) ; 0 \leq x \leq 1\}<1, \quad d=\sup \{w(x) ; 0 \leq x \leq 1\}>0 .
$$

Thus $E:=\{x \in[0,1] ; 0 \leq w(x) \leq 1\}$ is a compact set and mes $E>0$;
$\left(P_{2}\right) \xi(x)$ and $\eta(x)$ are continuous functions defined on $[a, 0]$ and $[1, b]$ respectively, where $a:=\min \{0, c\}, b:=\max \{1, d\}$; furthermore, $\xi(0)=\eta(1)=0 ; \xi(x) \geq 0$ as $\beta=0 ; \int_{x}^{0} e^{-\frac{\alpha}{\beta} s} \xi(s) d s \geq 0$ as $\beta>0 ; \eta(x) \geq 0$ as $\delta=0 ; \int_{1}^{x} e^{\frac{\gamma}{\delta} s} \eta(s) d s \geq 0$ as $\delta>0$.

For the case of $w(x) \equiv x, \operatorname{BVP}(1.1)$ is related to two point BVP of ODE for which Erbe and Wang ${ }^{[4]}$ have got the following theorem:

Theorem A. ${ }^{[4]}$ Assume that $w(x) \equiv x, \xi(x) \equiv 0, \eta(x) \equiv 0$ and $\left(A_{1}\right) f \in C([0,+\infty),[0,+\infty))$;
$\left(A_{2}\right) r \in C([0,1],[0,+\infty))$ and $r(x) \not \equiv 0$ for any subinterval of $[0,1]$;
$\left(A_{3}\right) \alpha, \beta, \gamma, \delta \geq 0, \rho:=\gamma \beta+\alpha \gamma+\alpha \delta>0$.
Then any one of the following is a sufficient condition for the existence of at least one positive solution of BVP (1.1):
(1) $\lim _{v \downarrow 0} \frac{f(v)}{v}=+\infty$ and $\lim _{v \uparrow+\infty} \frac{f(v)}{v}=0 \quad$ (sublinear case);
(2) $\lim _{v \downarrow 0} \frac{f(v)}{v}=0$ and $\lim _{v \uparrow+\infty} \frac{f(v)}{v}=+\infty \quad$ (superlinear case).

Motivated by [4], in this paper we shall extend the results of [4] to BVP (1.1). Firstly, we have the following hypotheses:
$\left(H_{1}\right) \alpha, \beta, \gamma, \delta \geq 0, \rho:=\gamma \beta+\alpha \gamma+\alpha \delta>0$;
$\left(H_{2}\right) \quad r(x)$ is a measurable function defined on [0, 1], and

$$
\begin{gathered}
0<\int_{E} h(x) r(x) d x \leq \int_{0}^{1} h(x) r(x) d x<+\infty \\
0<\int_{E} \phi_{1}(x) r(x) d x \leq \int_{0}^{1} \phi_{1}(x) r(x) d x<+\infty
\end{gathered}
$$

where $E$ is defined as in $\left(P_{1}\right) ; h(x):[0,1] \rightarrow[0,1]$ is defined by

$$
h(x)= \begin{cases}1, & \delta \beta>0 \\ x, & \beta=0, \delta>0 \\ 1-x, & \beta>0, \delta=0 \\ x(1-x), & \beta=\delta=0\end{cases}
$$

and $\phi_{1}(x)\left(\phi_{1}(x)>0, x \in(0,1)\right)$ is the eigenfunction related to the smallest eigenvalue $\lambda_{1}\left(\lambda_{1}>0\right)$ of the eigenvalue problem

$$
-\phi^{\prime \prime}=\lambda \phi, \quad \alpha \phi(0)-\beta \phi^{\prime}(0)=0, \quad \gamma \phi(1)+\delta \phi^{\prime}(1)=0 ;
$$

$\left(H_{3}\right) \quad f(y)$ is a nonnegative continuous function defined on $[0,+\infty)$.
Under the assumptions $\left(H_{1}\right)-\left(H_{3}\right)$, we allow that $r(x) \equiv 0$ on some subset of $E$, and $r(x)$ has some kind of singularities on $[0,1]$. For example, if $\beta=\delta=0$, then $\phi_{1}(x)=\sin \pi x$ and

$$
r(x)=x^{-m}(1-x)^{-n}, \quad 0<m<2,0<n<2,
$$

satisfies $\left(H_{2}\right)$.
To the best of the authors' knowledge, there has not been much work done about the positive solutions for the singular boundary value problems with deviating arguments, although they have importance in applications.

## 2 Main Theorem

First, we give the following definitions of solution and positive solution of BVP (1.1).

Definition. $y(x)$ is said to be a solution of BVP (1.1) if it satisfies the following:

1. $y(x)$ is nonnegative and continuous on $[a, b]$;
2. $y(x)=y(a ; x)$ as $x \in[a, 0]$, where $y(a ; x):[a, 0] \rightarrow[0,+\infty)$ is defined by

$$
y(a ; x)= \begin{cases}e^{\frac{\alpha}{\beta} x}\left(\frac{1}{\beta} \int_{x}^{0} e^{-\frac{\alpha}{\beta} s} \xi(s) d s+y(0)\right), & \beta>0  \tag{2.1}\\ \frac{1}{\alpha} \xi(x), & \beta=0\end{cases}
$$

3. $y(x)=y(b ; x)$ as $x \in[1, b]$, where $y(b ; x):[1, b] \rightarrow[0,+\infty)$ is defined by

$$
y(b ; x)= \begin{cases}e^{-\frac{\gamma}{\delta} x}\left(\frac{1}{\delta} \int_{1}^{x} e^{\frac{\gamma}{\delta}} \eta(s) d s+e^{\frac{\gamma}{\delta}} y(1)\right), & \delta>0  \tag{2.2}\\ \frac{1}{\gamma} \eta(x), & \delta=0\end{cases}
$$

4. while $\delta \beta>0, y^{\prime}(x)$ exists and is absolutely continuous on $[0,1]$; while $\beta=0, \delta>$ $0, y^{\prime}(x)$ exists and is locally absolutely continuous on ( 0,1$]$; while $\beta>0, \delta=0$, $y^{\prime}(x)$ exists and is locally absolutely continuous on $[0,1)$; while $\beta=\delta=0, y^{\prime}(x)$ exists and is locally absolutely continuous on ( 0,1 );
5. $y^{\prime \prime}(x)=-r(x) f(y(w(x)))$ for $x \in(0,1)$ almost everywhere.

Furthermore, a solution $y(x)$ of (1.1) is called a positive solution if $y(x)>0$ for $x \in(0,1)$.

Suppose that $y(x)$ is a solution of BVP (1.1), then it could be expressed as

$$
y(x)= \begin{cases}y(a ; x), & a \leq x \leq 0,  \tag{2.3}\\ \int_{0}^{1} G(x, t) r(t) f(y(w(t))) d t, & 0 \leq x \leq 1, \\ y(b ; x), & 1 \leq x \leq b,\end{cases}
$$

and Green's function

$$
G(x, t):= \begin{cases}\frac{1}{\rho}(\delta+\gamma-\gamma x)(\beta+\alpha t), & 0 \leq t \leq x \leq 1 \\ \frac{1}{\rho}(\delta+\gamma-\gamma t)(\beta+\alpha x), & 0 \leq x \leq t \leq 1\end{cases}
$$

where $\rho$ is given in $\left(H_{1}\right)$. It is obvious that $0<G(x, t) \leq G(t, t)$ for $(x, t) \in$ $(0,1) \times(0,1)$.

By an elementary calculation, one can find constants $\lambda$ and $B$ such that

$$
\begin{equation*}
\lambda B h(x) h(t) \leq G(x, t) \leq B h(t), \quad(x, t) \in[0,1] \times[0,1], \tag{2.4}
\end{equation*}
$$

where $h(x)$ is decided by $\left(H_{2}\right)$.
By using (2.3) and (2.4), we know that for every solution $y(x)$ of BVP (1.1), one has

$$
\left\{\begin{array}{l}
\|y\|_{[0,1]} \leq B \int_{0}^{1} h(t) r(t) f(y(w(t))) d t,  \tag{2.5}\\
y(x) \geq \lambda\|y\|_{[0,1]} h(x), \quad x \in[0,1],
\end{array}\right.
$$

where $\|y\|_{[0,1]}:=\sup \{|y(x)| ; \quad 0 \leq x \leq 1\}$.
Choose $\sigma \in\left(0, \frac{1}{4}\right)$ such that

$$
\begin{equation*}
\int_{E_{\sigma}} h(s) r(s) d s>0, \quad \int_{E_{\sigma}} \phi_{1}(s) r(s) d s>0 \tag{2.6}
\end{equation*}
$$

where $E_{\sigma}:=\{x \in E ; \sigma \leq w(x) \leq 1-\sigma\}$. In this paper, we always assume that $\sigma$ satisfies (2.6). Then we have from (2.5) that

$$
y(x) \geq \lambda\|y\|_{[0,1]} h(x) \geq \lambda \sigma_{o}\|y\|_{[0,1]}, \quad x \in[\sigma, 1-\sigma],
$$

here

$$
\sigma_{o}= \begin{cases}1, & \delta \beta>0  \tag{2.7}\\ \sigma, & \beta>0, \delta=0 \quad \text { or } \quad \beta=0, \delta>0 \\ \sigma(1-\sigma), & \delta=\beta=0\end{cases}
$$

The following theorem is our main result.
Theorem 1. If $\left(P_{1}\right),\left(P_{2}\right),\left(H_{1}\right)-\left(H_{3}\right)$ are satisfied, then any one of the following is a sufficient condition for the existence of at least one positive solution of BVP(1.1):
$\left(H_{4}\right) \lim \inf _{v \rightarrow 0+} \frac{f(v)}{v}>k \lambda_{1}, \quad \lim \sup _{v \rightarrow+\infty} \frac{f(v)}{v}<q \lambda_{1} ;$
$\left(H_{5}\right) \lim \inf _{v \rightarrow+\infty} \frac{f(v)}{v}>k \lambda_{1}, \quad \lim \sup _{v \rightarrow 0+} \frac{f(v)}{v}<q \lambda_{1}, \quad \xi(x) \equiv 0, \eta(x) \equiv 0 ;$
where $k>0$ is large enough such that

$$
k \lambda \sigma_{o} \int_{E_{\sigma}} r(x) \phi_{1}(x) d x \geq \int_{0}^{1} \phi_{1}(x) d x
$$

and $q>0$ is small enough such that

$$
q \int_{0}^{1} r(x) \phi_{1}(x) d x \leq \lambda \sigma_{o} \int_{\sigma}^{1-\sigma} \phi_{1}(x) d x
$$

( $\lambda$ and $\sigma_{o}$ are defined as in (2.4) and (2.7) respectively).
Corollary. Using the following $\left(H_{6}\right)$ or $\left(H_{7}\right)$ instead of $\left(H_{4}\right)$ or $\left(H_{5}\right)$, the conclusion of Theorem 1 is true.
$\left(H_{6}\right) \lim _{v \downarrow 0} \frac{f(v)}{v}=+\infty, \quad \lim _{v \uparrow+\infty} \frac{f(v)}{v}=0 \quad$ (sublinear);
$\left(H_{7}\right) \lim _{v \downarrow 0} \frac{f(v)}{v}=0, \quad \lim _{v \uparrow+\infty} \frac{f(v)}{v}=+\infty \quad$ (superlinear), $\quad \xi(x) \equiv 0, \eta(x) \equiv 0$.

It is obvious that our corollary is an extension of Theorem A, and Theorem 1 is an improvement of Theorem A even for the case $w(x)=x$. We remark here that only if $\delta \beta>0$ and $r(x)$ is continuous on [ 0,1 ], every positive solution of BVP (1.1) belongs to $C^{1}[a, b] \cap C^{2}[0,1]$.

## 3 Proof of Theorem

In this section, we shall show the conclusion of Theorem 1 only for the situation $\beta>0, \delta=0$. The arguments for the other three cases are similar. First we give a lemma which will be used later (see [5] or [11]).

Lemma 1. Assume that $X$ is a Banach space, and $K \subset X$ is a cone in $X$. Let $K_{p}=\{u \in K ;\|u\| \leq p\}$. Furthermore, assume that $\Phi: K \rightarrow K$ is a compact map, and $\Phi u \neq u$ for $u \in \partial K_{p}=\{u \in K ;\|u\|=p\}$. Then one has the following conclusions:

1. if $\|u\| \leq\|\Phi u\|$ for $u \in \partial K_{p}$, then $i\left(\Phi, K_{p}, K\right)=0$;
2. if $\|u\| \geq\|\Phi u\|$ for $u \in \partial K_{p}$, then $i\left(\Phi, K_{p}, K\right)=1$.

If $u_{o}(x)$ is a solution of BVP (1.1) for $f \equiv 0$, then it can be expressed as

$$
u_{o}(x)= \begin{cases}\frac{1}{\beta} e^{\frac{\alpha}{\beta} x} \int_{x}^{0} e^{-\frac{\alpha}{\beta} s} \xi(s) d s, & a \leq x \leq 0  \tag{3.1}\\ 0, & 0 \leq x \leq 1 \\ \frac{1}{\gamma} \eta(x), & 1 \leq x \leq b\end{cases}
$$

If $y(x)$ is a solution of $\operatorname{BVP}(1.1)$, let $u(x)=y(x)-u_{o}(x)$, noting that $u(x) \equiv y(x)$ as $0 \leq x \leq 1$, then by using (3.1), we have

$$
u(x)= \begin{cases}e^{\frac{\alpha}{\beta} x} u(0), & a \leq x \leq 0  \tag{3.2}\\ \int_{0}^{1} G(x, t) r(t) f\left(u(w(t))+u_{o}(w(t))\right) d t, & 0 \leq x \leq 1 \\ 0, & 1 \leq x \leq b\end{cases}
$$

Let $K$ be a cone in the Banach space $X=C[a, b]$ which is defined as

$$
K=\left\{u \in C[a, b] ; \quad u(x) \geq \lambda \sigma_{o}\|u\|, x \in[\sigma, 1-\sigma]\right\}
$$

where $\|u\|:=\sup \{|u(x)| ; \quad a \leq x \leq b\}$ (noting that $\|u\|_{[0,1]}$ is defined as in (2.5)).
Define an operator $\Phi: K \rightarrow K$ by

$$
(\Phi u)(x)= \begin{cases}e^{\frac{\alpha}{\beta} x} \int_{0}^{1} G(0, t) r(t) f\left(u(w(t))+u_{o}(w(t))\right) d t, & a \leq x \leq 0  \tag{3.3}\\ \int_{0}^{1} G(x, t) r(t) f\left(u(w(t))+u_{o}(w(t))\right) d t, & 0 \leq x \leq 1 \\ 0, & 1 \leq x \leq b\end{cases}
$$

Then we have the following four lemmas.
Lemma 2. $\Phi(K) \subset K$.
Proof. It is obvious that $0 \leq(\Phi u)(x) \leq(\Phi u)(0)$ as $a \leq x \leq 0$, then one has $\|\Phi u\|=\|\Phi u\|_{[0,1]}$. We have from (2.4) and (3.3) that (noting that $h(x)=1-x$ )

$$
\|\Phi u\|_{[0,1]} \leq B \int_{0}^{1}(1-t) r(t) f\left(u(w(t))+u_{o}(w(t))\right) d t
$$

thus we have

$$
\begin{aligned}
(\Phi u)(x) & \geq \lambda B \int_{0}^{1}(1-x)(1-t) r(t) f\left(u(w(t))+u_{o}(w(t))\right) d t, \\
& \geq \lambda(1-x)\|\Phi u\|_{[0,1]}, \quad x \in[0,1] .
\end{aligned}
$$

Thus $(\Phi u)(x) \geq \lambda \sigma_{o}\|\Phi u\|, \quad \sigma \leq x \leq 1-\sigma$, i.e. $\Phi(K) \subset K$.
Lemma 3. $\Phi: K \rightarrow K$ is completely continuous.
Proof. We can obtain the continuity of $\Phi$ from the continuity of $f$. In fact, if $u_{n}, u \in K$ and $\left\|u_{n}-u\right\| \rightarrow 0$ as $n \rightarrow \infty$, then we have from (3.3) that for $a \leq x \leq b$,

$$
\begin{aligned}
& \left|\left(\Phi u_{n}\right)(x)-(\Phi u)(x)\right| \\
\leq & \max _{0 \leq x \leq 1}\left|f\left(u_{n}(w(x))+u_{o}(w(x))\right)-f\left(u(w(x))+u_{o}(w(x))\right)\right| B \int_{0}^{1}(1-t) r(t) d t
\end{aligned}
$$

which implies that $\left\|\Phi u_{n}-\Phi u\right\| \rightarrow 0$ as $n \rightarrow \infty$.
Suppose that $A \subset K$ is a bounded set, and there exists a constant $M_{1}>0$ such that $\|u\| \leq M_{1}$ for $u \in A$. Let $\left\|u_{o}\right\|=M_{2}$, then $\left\|u+u_{o}\right\| \leq M_{1}+M_{2}=M$ for $u \in A$. We have from (3.3) that

$$
\begin{equation*}
\|\Phi u\| \leq B \max _{0 \leq v \leq M} f(v) \int_{0}^{1}(1-t) r(t) d t \tag{3.4}
\end{equation*}
$$

Thus $\Phi(A)$ is bounded in $K$. Now it is easy to see that $\Phi u \in C^{1}[a, 1) \cap C[a, b]$, and

$$
\begin{align*}
(\Phi u)^{\prime}(x)= & \frac{-1}{\beta+\alpha} \int_{0}^{x}(\beta+\alpha t) r(t) f\left(u(w(t))+u_{o}(w(t))\right) d t \\
& +\frac{\alpha}{\beta+\alpha} \int_{x}^{1}(1-t) r(t) f\left(u(w(t))+u_{o}(w(t))\right) d t, \quad 0 \leq x<1,  \tag{3.5}\\
(\Phi u)^{\prime}(x)= & \frac{\alpha}{\beta} e^{\frac{\alpha}{\beta} x} \int_{0}^{1} G(0, t) r(t) f\left(u(w(t))+u_{o}(w(t))\right) d t, \quad a \leq x \leq 0 .
\end{align*}
$$

For $u \in A, 0 \leq x \leq 1$, we have

$$
\begin{equation*}
(\Phi u)(x) \leq F(x):=\max _{0 \leq v \leq M} f(v) \int_{0}^{1} G(x, t) r(t) d t, \quad 0 \leq x \leq 1 . \tag{3.6}
\end{equation*}
$$

Noting the facts that $F(1)=0$ and the continuity of $F(x)$ on $[0,1]$, we have from (3.6) that for any $\epsilon>0$, one can find a $\delta_{1}>0$ (independent with $u$ ) such that, $0<\delta_{1}<\frac{1}{4}$ and

$$
\begin{equation*}
(\Phi u)(x)<\frac{\epsilon}{2}, \quad 1-2 \delta_{1}<x<1 . \tag{3.7}
\end{equation*}
$$

On the other hand, for $x \in\left[0,1-\delta_{1}\right]$ one has

$$
\begin{aligned}
\left|(\Phi u)^{\prime}(x)\right| & \leq \max _{0 \leq v \leq M} f(v)\left\{\int_{0}^{1-\delta_{1}} r(t) d t+\int_{0}^{1}(1-t) r(t) d t\right\} \\
& \leq \frac{1+\delta_{1}}{\delta_{1}} \max _{0 \leq v \leq M} f(v) \int_{0}^{1}(1-t) r(t) d t=L_{1} .
\end{aligned}
$$

For $x \in[a, 0]$, one has from (3.5) and (3.4) that

$$
\left|(\Phi u)^{\prime}(x)\right| \leq \frac{\alpha}{\beta}|(\Phi u)(x)| \leq \frac{\alpha}{\beta} B \max _{0 \leq v \leq M} f(v) \int_{0}^{1} r(t)(1-t) d t=L_{2} .
$$

Let $\delta_{2}=\frac{\epsilon}{\max \left\{L_{1}, L_{2}\right\}}$, then for $x_{1}, x_{2} \in\left[a, 1-\delta_{1}\right],\left|x_{1}-x_{2}\right|<\delta_{2}$, we have

$$
\begin{equation*}
\left|(\Phi u)\left(x_{1}\right)-(\Phi u)\left(x_{2}\right)\right| \leq \max \left\{L_{1}, L_{2}\right\}\left|x_{1}-x_{2}\right|<\epsilon \tag{3.8}
\end{equation*}
$$

Define $\delta_{o}=\min \left\{\delta_{1}, \delta_{2}\right\}$, then by using (3.7) - (3.8) and the fact that $(\Phi u)(x) \equiv 0$ for $x \in[1, b]$, we obtain that

$$
\left|(\Phi u)\left(x_{1}\right)-(\Phi u)\left(x_{2}\right)\right|<\epsilon,
$$

for $x_{1}, x_{2} \in[a, b],\left|x_{1}-x_{2}\right|<\delta_{o}$, which implies that $\Phi(A)$ is equicontinuous. In view of the Arzela-Ascoli lemma, we know that $\bar{\Phi}(A)$ is a compact set; thus $\Phi: K \rightarrow K$ is completely continuous.

Lemma 4. $\left(H_{6}\right)$ implies that there exists $r_{o}, R_{o}: 0<r_{o}<R_{o}$ such that

$$
i\left(\Phi, K_{r}, K\right)=0, \quad 0<r \leq r_{o} ; \quad i\left(\Phi, K_{R}, K\right)=1, \quad R \geq R_{o}
$$

Proof. By using the first equality of $\left(H_{6}\right)$ we can choose $r_{o}>0$ such that

$$
f(v) \geq M v, \quad 0 \leq v \leq r_{o}
$$

where $M$ satisfies $\lambda^{2} T B \sigma_{o} M>2$ and

$$
T=\int_{E_{\sigma}}(1-s) r(s) d s
$$

If $u \in \partial K_{r}\left(0<r \leq r_{o}\right)$, one has

$$
\begin{equation*}
u(x) \geq \lambda \sigma_{o}\|u\|=\lambda \sigma_{o} r, \quad x \in[\sigma, 1-\sigma] . \tag{3.9}
\end{equation*}
$$

Then we obtain ( noting that $u_{o}(x) \equiv 0$ as $x \in[0,1]$ )

$$
\begin{aligned}
(\Phi u)\left(\frac{1}{2}\right) & =\int_{0}^{1} G\left(\frac{1}{2}, s\right) r(s) f\left(u(w(s))+u_{o}(w(s))\right) d s \\
& \geq \frac{1}{2} \lambda B \int_{E_{\sigma}}(1-s) r(s) f(u(w(s))) d s \\
& \geq \frac{1}{2} \lambda^{2} B \sigma_{o} r T M \\
& >r=\|u\| .
\end{aligned}
$$

This leads to

$$
\|\Phi u\|>\|u\|, \quad \forall u \in \partial K_{r} .
$$

Thus we have from Lemma $1 i\left(\Phi, K_{r}, K\right)=0$, for $0<r \leq r_{o}$.
On the other hand, the second equality of $\left(H_{6}\right)$ leads to: for $\forall \epsilon>0$, there is a $R^{\prime}>r_{o}+\left\|u_{o}\right\|$ such that

$$
\begin{equation*}
f(v) \leq \epsilon v, \quad v>R^{\prime} \tag{3.10}
\end{equation*}
$$

where $\epsilon$ satisfies

$$
\begin{equation*}
\epsilon B\left(1+\left\|u_{o}\right\|\right) \int_{0}^{1}(1-s) r(s) d s<\frac{1}{2} . \tag{3.11}
\end{equation*}
$$

Choose

$$
\begin{equation*}
R_{o}>1+2 B \max \left\{f(v) ; 0 \leq v \leq R^{\prime}+\left\|u_{o}\right\|\right\} \int_{0}^{1}(1-s) r(s) d s \tag{3.12}
\end{equation*}
$$

Thus, if $u \in \partial K_{R}$ and $R \geq R_{o}$, then we have from (3.10)-(3.12) that

$$
\begin{aligned}
(\Phi u)(x) \leq & B \int_{0}^{1}(1-s) r(s) f\left(u(w(s))+u_{o}(w(s))\right) d s \\
= & B \int_{u(w(s))>R^{\prime}}(1-s) r(s) f\left(u(w(s))+u_{o}(w(s))\right) d s \\
& +B \int_{0 \leq u(w(s)) \leq R^{\prime}}(1-s) r(s) f\left(u(w(s))+u_{o}(w(s))\right) d s \\
\leq & \epsilon B\left(\|u\|+\left\|u_{o}\right\|\right) \int_{0}^{1}(1-s) r(s) d s \\
& \quad+B \max \left\{f(v) ; 0 \leq v \leq R^{\prime}+\left\|u_{o}\right\|\right\} \int_{0}^{1}(1-s) r(s) d s \\
< & \frac{1}{2}\|u\|+\frac{1}{2}+B \max \left\{f(v) ; 0 \leq v \leq R^{\prime}+\left\|u_{o}\right\|\right\} \int_{0}^{1}(1-s) r(s) d s \\
< & \frac{1}{2}\|u\|+\frac{1}{2} R, \quad 0 \leq x \leq 1 .
\end{aligned}
$$

That is

$$
\|\Phi u\|=\|\Phi u\|_{[0,1]}<\|u\|, \quad \forall u \in \partial K_{R},
$$

Thus $i\left(\Phi, K_{R}, K\right)=1$ for $R \geq R_{o}$.
Lemma 5. ( $H_{7}$ ) implies that there exists $r_{o}, R_{o}: 0<r_{o}<R_{o}$ such that

$$
i\left(\Phi, K_{r}, K\right)=1, \quad 0<r \leq r_{o} ; \quad i\left(\Phi, K_{R}, K\right)=0, \quad R \geq R_{o} .
$$

Proof. Since $\xi(x) \equiv 0, \eta(x) \equiv 0$, we have $u_{o}(x) \equiv 0$. By the first equality of $\left(H_{7}\right)$, one can choose a $r_{o}>0$ such that

$$
\begin{equation*}
f(v) \leq \epsilon v, \quad 0 \leq v \leq r_{o}, \tag{3.13}
\end{equation*}
$$

where $\epsilon>0$ satisfies

$$
\begin{equation*}
0<\epsilon B \int_{0}^{1}(1-s) r(s) d s<\frac{1}{2} . \tag{3.14}
\end{equation*}
$$

If $u \in \partial K_{r}, 0<r \leq r_{o}$, then we have from (3.3), (3.13) and (3.14) that

$$
\begin{aligned}
0 \leq(\Phi u)(x) & \leq B \int_{0}^{1}(1-s) r(s) f(u(w(s))) d s \\
& \leq \epsilon B \int_{0}^{1}(1-s) r(s) u(w(s)) d s \\
& \leq \epsilon B\|u\| \int_{0}^{1}(1-s) r(s) d s \\
& <\|u\|, \quad 0 \leq x \leq 1,
\end{aligned}
$$

That is

$$
\|\Phi u\|=\|\Phi u\|_{[0,1]}<\|u\|, \quad \forall u \in \partial K_{r} .
$$

So we have the conclusion that $i\left(\Phi, K_{r}, K\right)=1,0<r \leq r_{o}$.
On the other hand, the second equality of $\left(H_{7}\right)$ implies that $\forall M>0$, there is an $R_{o}>r_{o}$ such that

$$
\begin{equation*}
f(v) \geq M v, \quad v>\lambda \sigma_{o} R_{o} \tag{3.15}
\end{equation*}
$$

here we choose $M>0$ such that $\lambda^{2} T B \sigma_{o} M>2$. For $u \in \partial K_{R}, R \geq R_{o}$, we have from the definition of $K_{R}$ that

$$
\begin{equation*}
u(x) \geq \lambda \sigma_{o}\|u\|=\lambda \sigma_{o} R, \quad x \in[\sigma, 1-\sigma] . \tag{3.16}
\end{equation*}
$$

Thus we have from (3.3),(3.15)-(3.16) that

$$
\begin{aligned}
(\Phi u)\left(\frac{1}{2}\right) & =\int_{0}^{1} G\left(\frac{1}{2}, s\right) r(s) f(u(w(s))) d s \\
& \geq \frac{1}{2} \lambda B \int_{E_{\sigma}}(1-s) r(s) f(u(w(s))) d s \\
& \geq \frac{1}{2} \lambda^{2} B \sigma_{\sigma} R M \int_{E_{\sigma}}(1-s) r(s) d s \\
& =\frac{1}{2} \lambda^{2} B \sigma_{o} R T M \\
& >R=\|u\|,
\end{aligned}
$$

which leads to

$$
\|\Phi u\|>\|u\| \quad \forall u \in \partial K_{R}
$$

Thus $i\left(\Phi, K_{R}, K\right)=0$ for $R \geq R_{o}$.
Now by using the above lemmas, we can show the conclusions of Theorem 1.
Proof of Theorem 1. For $0<m<1<n$, define $f_{1}(u)=u^{m}, f_{2}(u)=u^{n}, \quad u \geq$ 0 , so that $f_{1}(u)$ satisfies $\left(H_{6}\right)$ and $f_{2}(u)$ satisfies $\left(H_{7}\right)$. Define $\Phi_{i}: K \rightarrow K(i=1,2)$ as follows:

$$
\left(\Phi_{i} u\right)(x)= \begin{cases}e^{\frac{\alpha}{\beta} x} \int_{0}^{1} G(0, t) r(t) f_{i}\left(u(w(t))+u_{o}(w(t))\right) d t, & a \leq x \leq 0  \tag{3.17}\\ \int_{0}^{1} G(x, t) r(t) f_{i}\left(u(w(t))+u_{o}(w(t))\right) d t, & 0 \leq x \leq 1 \\ 0, & 1 \leq x \leq b\end{cases}
$$

Then $\Phi_{i} u(i=1,2)$ are completely continuous operators. One has from Lemma 4-5 that

$$
\begin{equation*}
i\left(\Phi_{1}, K_{r}, K\right)=0, \quad 0<r \leq r_{o} ; \quad i\left(\Phi_{1}, K_{R}, K\right)=1, \quad R \geq R_{o} \tag{3.18}
\end{equation*}
$$

and

$$
\begin{equation*}
i\left(\Phi_{2}, K_{r}, K\right)=1, \quad 0<r \leq r_{o} ; \quad i\left(\Phi_{2}, K_{R}, K\right)=0, \quad R \geq R_{o} \tag{3.19}
\end{equation*}
$$

Define $H_{i}(s, u)=(1-s) \Phi u+s \Phi_{i} u(i=1,2)$ so that for any $s \in[0,1], H_{i}$ is a completely continuous operator. Furthermore, for any $\omega>0$ and $i=1,2$, we have

$$
\left|H_{i}\left(s_{1}, u\right)-H_{i}\left(s_{2}, u\right)\right| \leq\left|s_{1}-s_{2}\right|\left[\left\|\Phi_{i} u\right\|+\|\Phi u\|\right]
$$

as $s_{1}, s_{2} \in[0,1], u \in K_{\omega}$. Note that $\left\|\Phi_{i} u\right\|+\|\Phi u\|$ is uniformly bounded in $K_{\omega}$. Thus $H_{i}(s, u)$ is continuous on $u \in K_{\omega}$ uniformly for $s \in[0,1]$. According to Lemma 7.2.3 in [18], we conclude that $H_{i}(s, u)$ is a completely continuous operater on $[0,1] \times K_{\omega}$.

Suppose that $\left(H_{4}\right)$ holds. By using the first inequality of $\left(H_{4}\right)$ and the definition of $f_{1}$, one can find $\epsilon>0$ and $r_{1}: 0<r_{1} \leq r_{o}$ such that

$$
\begin{cases}f(u) \geq\left(k \lambda_{1}+\epsilon\right) u, & 0 \leq u \leq r_{1},  \tag{3.20}\\ f_{1}(u) \geq\left(k \lambda_{1}+\epsilon\right) u, & 0 \leq u \leq r_{1} .\end{cases}
$$

In what follows, we shall show that $H_{1}(s, u) \neq u$ for $u \in \partial K_{r_{1}}$ and $s \in[0,1]$. If this is not true, then there exist $s_{1}: 0 \leq s_{1} \leq 1$ and $u_{1} \in \partial K_{r_{1}}$ such that $H_{1}\left(s_{1}, u_{1}\right)=u_{1}$. Note that $u_{1}(x)$ satisfies

$$
\begin{array}{rlr}
-u_{1}^{\prime \prime}(x)= & \left(1-s_{1}\right) r(x) f\left(u_{1}(w(x))+u_{o}(w(x))\right)  \tag{3.21}\\
& +s_{1} r(x) f_{1}\left(u_{1}(w(x))+u_{o}(w(x))\right), \quad 0<x<1 ;
\end{array}
$$

and

$$
\begin{cases}\alpha u_{1}(x)-\beta u_{1}^{\prime}(x)=0, & a \leq x \leq 0,  \tag{3.22}\\ u_{1}(x)=0, & 1 \leq x \leq b .\end{cases}
$$

Multiplying both sides of (3.21) by $\phi_{1}(x)$ and then integrating it from 0 to 1 , after two times of integrating by parts, we get from (3.22) that

$$
\begin{align*}
\lambda_{1} \int_{0}^{1} u_{1}(x) \phi_{1}(x) d x & =\int_{0}^{1} \phi_{1}(x)\left[\left(1-s_{1}\right) r(x) f\left(u_{1}(w(x))+u_{o}(w(x))\right)\right.  \tag{3.23}\\
& \left.+s_{1} r(x) f_{1}\left(u_{1}(w(x))+u_{o}(w(x))\right)\right] d x .
\end{align*}
$$

Noting that $u_{o}(w(x)) \equiv 0$ as $x \in E_{\sigma}$, we obtain from (3.20) and $\left(H_{4}\right)$ that

$$
\begin{align*}
\lambda_{1} \int_{0}^{1} u_{1}(x) \phi_{1}(x) d x & \left.\geq \int_{E_{\sigma}} \phi_{1}(x) r(x)\left[\left(1-s_{1}\right) f\left(u_{1}(w(x))\right)\right)+s_{1} f_{1}\left(u_{1}(w(x))\right)\right] d x \\
& \geq \int_{E_{\sigma}} \phi_{1}(x) r(x)\left[\left(1-s_{1}\right)\left(k \lambda_{1}+\epsilon\right) u_{1}(w(x))\right. \\
& \left.+s_{1}\left(k \lambda_{1}+\epsilon\right) u_{1}(w(x))\right] d x \\
\geq & \geq\left(\lambda_{1}+\frac{\epsilon}{k}\right) k \lambda \sigma_{o}\left\|u_{1}\right\| \int_{E_{\sigma}} \phi_{1}(x) r(x) d x \\
\geq & \left(\lambda_{1}+\frac{\epsilon}{k}\right)\left\|u_{1}\right\| \int_{0}^{1} \phi_{1}(x) d x . \tag{3.24}
\end{align*}
$$

We also have

$$
\begin{equation*}
\lambda_{1} \int_{0}^{1} u_{1}(x) \phi_{1}(x) d x \leq \lambda_{1}\left\|u_{1}\right\| \int_{0}^{1} \phi_{1}(x) d x \tag{3.25}
\end{equation*}
$$

which together with (3.24) leads to

$$
\lambda_{1} \geq \lambda_{1}+\frac{\epsilon}{k} .
$$

This is impossible. Thus $H_{1}(s, u) \neq u$ for $u \in \partial K_{r_{1}}$ and $s \in[0,1]$. In view of the homotopic invariant property of topological degree (see [9] or [18]) and (3.18) we know that

$$
\begin{align*}
i\left(\Phi, K_{r_{1}}, K\right) & =i\left(H_{1}(0, \cdot), K_{r_{1}}, K\right) \\
& =i\left(H_{1}(1, \cdot), K_{r_{1}}, K\right)=i\left(\Phi_{1}, K_{r_{1}}, K\right)=0 . \tag{3.26}
\end{align*}
$$

On the other hand, according to the second inequality of $\left(H_{4}\right)$, there exist $\epsilon>0$ and $R^{\prime}>R_{o}$ such that

$$
f(u) \leq\left(q \lambda_{1}-\epsilon\right) u, \quad u \geq R^{\prime} .
$$

If $C=\max _{0 \leq u \leq R^{\prime}}\left|f(u)-\left(q \lambda_{1}-\epsilon\right) u\right|+1$, then we deduce that

$$
\begin{equation*}
f(u) \leq\left(q \lambda_{1}-\epsilon\right) u+C, \quad \forall u \geq 0 \tag{3.27}
\end{equation*}
$$

Define $H(s, u)=s \Phi u, s \in[0,1]$. We shall show that there exists a $R_{1} \geq R^{\prime}$ such that

$$
\begin{equation*}
H(s, u) \neq u, \quad \forall s \in[0,1], u \in K, \quad\|u\| \geq R_{1} . \tag{3.28}
\end{equation*}
$$

If $\exists s_{1} \in[0,1], u_{1} \in K$ such that $H\left(s_{1}, u_{1}\right)=u_{1}$, then it is similar to the argument of (3.24)-(3.25) that

$$
\begin{align*}
& \lambda_{1} \int_{0}^{1} u_{1}(x) \phi_{1}(x) d x \\
= & s_{1} \int_{0}^{1} r(x) \phi_{1}(x) f\left(u_{1}(w(x))+u_{o}(w(x))\right) d x \\
\leq & q\left(\lambda_{1}-\frac{\epsilon}{q}\right)\left\|u_{1}+u_{o}\right\| \int_{0}^{1} r(x) \phi_{1}(x) d x+C \int_{0}^{1} r(x) \phi_{1}(x) d x  \tag{3.29}\\
\leq & q\left(\lambda_{1}-\frac{\epsilon}{q}\right)\left\|u_{1}\right\| \int_{0}^{1} r(x) \phi_{1}(x) d x+C_{1} \int_{0}^{1} r(x) \phi_{1}(x) d x,
\end{align*}
$$

and

$$
\begin{align*}
\lambda_{1} \int_{0}^{1} u_{1}(x) \phi_{1}(x) d x & \geq \lambda_{1} \lambda \sigma_{o}\left\|u_{1}\right\| \int_{\sigma}^{1-\sigma} \phi_{1}(x) d x \\
& \geq \lambda_{1} q\left\|u_{1}\right\| \int_{0}^{1} r(x) \phi_{1}(x) d x, \tag{3.30}
\end{align*}
$$

where $C_{1}=q\left(\lambda_{1}-\frac{\epsilon}{q}\right)\left\|u_{o}\right\|+C$. Combining (3.29) with (3.30), we have

$$
\left\|u_{1}\right\| \leq \frac{C_{1}}{\epsilon}=\bar{R} .
$$

Define $R_{1}=\max \left\{R^{\prime}, \bar{R}\right\}$, then (3.28) is true. By the homotopic invariant property of topological degree, one has

$$
\begin{align*}
i\left(\Phi, K_{R_{1}}, K\right) & =i\left(H(1, \cdot), K_{R_{1}}, K\right) \\
& =i\left(H(0, \cdot), K_{R_{1}}, K\right)=i\left(\theta, K_{R_{1}}, K\right)=1 \tag{3.31}
\end{align*}
$$

where $\theta$ is zero operator. In view of (3.26),(3.31), we obtain

$$
i\left(\Phi, K_{R_{1}} \backslash K_{r_{1}}, K\right)=1
$$

Thus $\Phi$ has a fixed point in $K_{R_{1}} \backslash K_{r_{1}}$.
Now assume that $\left(H_{5}\right)$ is true. The first inequality and the definition of $f_{2}$ lead to: $\exists \epsilon>0$ and $R^{\prime}>R_{o}$ such that

$$
\begin{cases}f(u) \geq\left(k \lambda_{1}+\epsilon\right) u, & u>R^{\prime} \\ f_{2}(u) \geq\left(k \lambda_{1}+\epsilon\right) u, & u>R^{\prime} .\end{cases}
$$

Let

$$
C=\max _{0 \leq u \leq R^{\prime}}\left|f(u)-\left(k \lambda_{1}+\epsilon\right) u\right|+\max _{0 \leq u \leq R^{\prime}}\left|f_{2}(u)-\left(k \lambda_{1}+\epsilon\right) u\right|+1,
$$

then we have

$$
\begin{equation*}
f(u) \geq\left(k \lambda_{1}+\epsilon\right) u-C, \quad f_{2}(u) \geq\left(k \lambda_{1}+\epsilon\right) u-C, \quad \forall u \geq 0 \tag{3.32}
\end{equation*}
$$

We want to show that $\exists R_{1} \geq R^{\prime}$ such

$$
\begin{equation*}
H_{2}(s, u) \neq u, \quad \forall s \in[0,1], u \in K,\|u\| \geq R_{1} . \tag{3.33}
\end{equation*}
$$

In fact, if there are $s_{1} \in[0,1], u_{1} \in K$ such that $H_{2}\left(s_{1}, u_{1}\right)=u_{1}$, then using (3.32), it is analogous to the argument of (3.24)-(3.25) that

$$
\begin{aligned}
\lambda_{1} \int_{0}^{1} u_{1}(x) \phi_{1}(x) d x & \geq \int_{E_{\sigma}} \phi_{1}(x) r(x)\left\{\left(1-s_{1}\right)\left[\left(k \lambda_{1}+\epsilon\right) u_{1}(w(x))-C\right]\right. \\
& \left.+s_{1}\left[\left(k \lambda_{1}+\epsilon\right) u_{1}(w(x))-C\right]\right\} d x \\
& \geq\left(\lambda_{1}+\frac{\epsilon}{k}\right) k \lambda \sigma_{o}\left\|u_{1}\right\| \int_{E_{\sigma}} \phi_{1}(x) r(x) d x-\int_{E_{\sigma}} C \phi_{1}(x) r(x) d x
\end{aligned}
$$

$$
\begin{equation*}
\lambda_{1} \int_{0}^{1} u_{1}(x) \phi_{1}(x) d x \leq \lambda_{1}\left\|u_{1}\right\| \int_{0}^{1} \phi_{1}(x) d x \tag{3.34}
\end{equation*}
$$

$$
\begin{equation*}
\leq \lambda_{1} k \lambda \sigma_{o}\left\|u_{1}\right\| \int_{E_{\sigma}} r(x) \phi_{1}(x) d x \tag{3.35}
\end{equation*}
$$

(3.34)-(3.35) lead to $\left\|u_{1}\right\| \leq \frac{C}{\lambda \sigma_{o} \epsilon}=\bar{R}$. Let $R_{1}=\max \left\{R^{\prime}, \bar{R}\right\}$. We obtain (3.33) and then we have

$$
\begin{equation*}
i\left(\Phi, K_{R_{1}}, K\right)=i\left(\Phi_{2}, K_{R_{1}}, K\right)=0 \tag{3.36}
\end{equation*}
$$

On the other hand, noting that $\xi(x) \equiv 0, \mu(x) \equiv 0$, one has $u_{o}(x) \equiv 0$ for $x \in[a, b]$. Define $H(s, u)$ as above. By the second inequality of $\left(H_{5}\right)$, there exist $\epsilon>0$ and $r_{1}: 0<r_{1} \leq r_{o}$ such that

$$
\begin{equation*}
f(u) \leq\left(q \lambda_{1}-\epsilon\right) u, \quad 0 \leq u \leq r_{1} . \tag{3.37}
\end{equation*}
$$

We could also show that

$$
H(s, u) \neq u, \quad \forall s \in[0,1], u \in \partial K_{r_{1}} .
$$

But we omit the details. Thus we obtain

$$
\begin{equation*}
i\left(\Phi, K_{r_{1}}, K\right)=i\left(\theta, K_{r_{1}}, K\right)=1 \tag{3.38}
\end{equation*}
$$

In view of (3.36),(3.38), we obtain

$$
i\left(\Phi, K_{R_{1}} \backslash K_{r_{1}}, K\right)=-1
$$

Thus $\Phi$ has a fixed point in $K_{R_{1}} \backslash K_{r_{1}}$.
Suppose that $u$ is the fixed point of $\Phi$ in $K_{R_{1}} \backslash K_{r_{1}}$. Let $y(x)=u(x)+u_{o}(x)$. Since $y(x)=u(x)$ for $x \in[0,1]$ and $0<r_{1} \leq\|u\|=\|u\|_{[0,1]}=\|y\|_{[0,1]} \leq R_{1}$, we have from (2.5) that $y(x)$ is the positive solution of $\operatorname{BVP}(1.1)$.

Thus we complete the proof.
Example. Let us introduce an example to illustrate the usage of our theorem. Consider the BVP:

$$
\begin{cases}y^{\prime \prime}(x)+r(x) y^{\frac{1}{2}}\left(x-\frac{1}{3}\right)=0, & 0<x<1  \tag{3.39}\\ y(x)=-\sin \pi x, & -\frac{1}{3} \leq x \leq 0, \\ y(1)=0 ; & \end{cases}
$$

where

$$
r(x)= \begin{cases}\pi^{2}(\sin \pi x)\left|\sin \pi\left(x-\frac{1}{3}\right)\right|^{-\frac{1}{2}}, & x \in\left[0, \frac{1}{3}\right) \cup\left(\frac{1}{3}, 1\right], \\ 0, & x=\frac{1}{3} .\end{cases}
$$

Then $w(x)=x-\frac{1}{3}, a=-\frac{1}{3}, b=1, f(v)=v^{\frac{1}{2}}, \alpha=\gamma=1, \beta=\delta=0, E=\left[\frac{1}{3}, 1\right]$. Since

$$
\frac{f(v)}{v}=\frac{v^{\frac{1}{2}}}{v}=v^{-\frac{1}{2}}
$$

we have $\lim _{v \rightarrow+\infty} \frac{f(v)}{v}=0, \quad \lim _{v \rightarrow 0+} \frac{f(v)}{v}=+\infty$. Thus $\left(P_{1}\right),\left(P_{2}\right),\left(H_{1}\right)-\left(H_{3}\right),\left(H_{6}\right)$ are satisfied and (3.39) has at least one positive solution $y(x)$. In fact,

$$
y(x)= \begin{cases}-\sin \pi x, & -\frac{1}{3} \leq x \leq 0 \\ \sin \pi x, & 0<x \leq 1\end{cases}
$$

is a positive solution of (3.39).

## References

[1] C. Bandle and M. K. Kwong, Semilinear Elliptic Problems in Annular Domains, J Appl Math Phys, 40 (1989), 245-257.
[2] C. Bandle, C. V. Coffman and M. Marcus, Nonlinear Elliptic Problems in Annular Domains. J Differential Equations, 69 (1987), 322-345.
[3] C. V. Coffman and M. Marcus, Existence and Uniqueness Results for Semilinear Dirichlet Problems in Annuli. Arch Rational Mech Anal, 108 (1987), 293-307.
[4] L. H. Erbe and H. Y. Wang, On the Existence of Positive Solutions of Ordinary Differential Equations. Proc Amer Math Soc, 120 (1994), 743-748.
[5] L. H. Erbe and S. C. Hu, Multiple Positive Solution of Some Boundary Value Problems, J.Math.Anal.Appl., 184 (1994), 640-648.
[6] L. H. Erbe and Q. K. Kong, Boundary Value Problems for Singular SecondOrder Functional Differential Equations. J Comput Appl Math, 53 (1994), 377388.
[7] L. H. Erbe, Z. C. Wang and L. T. Li, Boundary Value Problems for Second Order Mixed Type Functional Differential Equations, Boundary Value Problems for Functional Differential Equations, World Scientific, 1995, 143-151.
[8] X. Garaizar, Existence of Positive Radial Solutions for Semilinear Elliptic Problems in the Annulus. J Differential Equations, 70 (1987), 69-72.
[9] D. J. Guo, Nonlinear Functional Analysis (in Chinese), Shandong Scientific Press (Jinan), 1985, 302-303.
[10] B. S. Lalli and B. G. Zhang, Boundary Value Problems for Second Order Functional Differential Equations. Ann. of Diff. Eqs, 8 (1992), 261-268.
[11] Z. L. Liu and F. Y. Li, Multiple Positive Solution of Nonlinear Two-point Boundary Value Problems, J.Math. Anal. Appl., 203 (1996), 610-625.
[12] J. W. Lee and D. O'Regan, Existence Results for Differential Delay EquationsI, J. Differential Equations, 102 (1993), 342-359.
[13] J. W. Lee and D. O'Regan, Existence Results for Differential Delay EquationsII, Nonlinear Analysis, 17 (1991), 683-702.
[14] S. K. Ntouyas, Y. G. Sficas and P. CH. Tsamatos, An Existence Principle for Boundary Value Problems for Second Order Functional Differential Equations, Nonlinear Analysis, 20 (1993), 215-222.
[15] H. Y. Wang, On the Existence of Positive Solutions for Semilinear Elliptic Equations in the Annulus. J Differential Equations, 109 (1994), 1-8.
[16] P. X. Weng, Boundary Value Problems for Second Order Mixed Type Functional Differential Equations, Appl. Math.-JCU, 12B (1997), 155-164.
[17] J. S. W. Wong, On the Generalized Emden-Fowler Equation. SIAM Rev, 17 (1975), 339-360.
[18] Z. Y. Li and Q. X. Ye, Theory of Reaction-Diffusive Equations (in Chinese), Scientific Press (Peijing), 1990.


[^0]:    ${ }^{1}$ Supported by NSF of China and Guangdong Province

