

THE FREEZING METHOD FOR VOLTERRA INTEGRAL EQUATIONS IN A BANACH SPACE *

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Abstract

The "freezing" method for ordinary differential equations is extended to the Volterra integral equations in a Banach space of the type

$$x(t) - \int_0^t K(t, t-s)x(s)ds = f(t) \quad (t \geq 0),$$

where $K(t, s)$ is an operator valued function "slowly" varying in the first argument. Besides, sharp explicit stability conditions are derived.

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1 Introduction and statement of the basic lemma

Stability and boundedness of Volterra integral and integrodifferential equations have been extensively considered for a long time (see the well-known books [1, 4], recent papers [5, 8, 15, 16] and papers listed below). The basic method in the theory of stability and boundedness of Volterra integral equations is the direct Liapunov method. But finding the Liapunov functionals is a difficult mathematical problem. The other approach is connected with an interpretation of the Volterra equations as operator equations in appropriate spaces. Such an approach was used in many papers, cf. [3, 6, 7, 12, 14, 16] and references therein. In this paper, for a class of Volterra equations in a Banach space we establish explicit sufficient stability conditions which are also necessary stability conditions when the integral operator is a convolution. Our results improve the well known ones in the case of the considered equations.

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The approach suggested below is based on the extension of the "freezing" method which was introduced by V.M. Alekseev for linear ordinary differential equations cf. [2] (see also [9, Section 3.2]). That method was already extended to difference equations [11].

Let X be a Banach space with a norm $\|\cdot\|$ and the unit operator I , $R_+ := [0, \infty)$, and $C(\omega, X)$ is the space of continuous functions defined on a set $\omega \subset \mathbb{R}$ with values in X and equipped with the sup-norm $|\cdot|_{C(\omega)} = |\cdot|_{C(\omega, X)}$. $L^p(\omega, X)$ ($1 \leq p < \infty$) is the space of functions defined on ω with values in X and equipped with the

$$|f|_{L^p(\omega)} = \left[\int_{\omega} \|f(t)\|^p dt \right]^{1/p}.$$

Consider in X the equation

$$(1.1) \quad x(t) - \int_0^t K(t, t-s)x(s)ds = f(t) \quad (f \in C(R_+, X), t \geq 0),$$

where $K(t, s)$ is a functions defined on $[0 \leq s \leq t < \infty]$, whose values are bounded operators in X , and for any fixed $\tau \geq 0$, $K(\tau, \cdot)$ is integrable and bounded on R_+ . In addition,

$$(1.2) \quad \int_0^t \|K(t, s) - K(\tau, s)\| ds \leq q|t - \tau| \quad (q = const; t, \tau \geq 0).$$

A solution of Equation (1.1) is a continuous function defined on R_+ and satisfying (1.1) for all finite $t > 0$. The existence of solutions under consideration is checked below.

Note that the approach suggested below enables us to consider also the equation

$$x(t) - \int_0^t K(t-s, s)x(s)ds = f(t) \quad (t \geq 0)$$

under condition (1.2). It is clear that under (1.2) the function $K(\tau, s)$, for a fixed τ , admits the Laplace transform

$$\tilde{K}_\tau(z) := \int_0^\infty e^{-zs} K(\tau, s) ds \quad (Re z \geq c_0 = const).$$

Besides, it is assumed that the operator $W_\tau(z) := I - \tilde{K}_\tau(z)$ is invertible for all $z \in C_+ := \{z \in \mathbb{C} : Re z \geq 0\}$ and $W_\tau^{-1}(iy) \in L^1(\mathbb{R})$. Introduce the "local Green function"

$$G_\tau(t) := \frac{1}{2\pi} \int_{-\infty}^\infty e^{iyt} W_\tau^{-1}(iy) dy.$$

We will say that Equation (1.1) is stable, if for any $f \in C(R_+, X)$ a solution x of (1.1) satisfies the inequality

$$(1.3) \quad |x|_{C(R_+)} \leq a_0 |f|_{C(R_+)},$$

where the constant a_0 does not depend on f .

Lemma 1.1 Under condition (1.2), let

$$(1.4) \quad q \int_0^\infty s \sup_{\tau \geq 0} \|G_\tau(s)\| ds < 1.$$

Then Equation (1.1) is stable. Moreover, constant a_0 in (1.3) is explicitly pointed below.

This lemma is proved in the next section.

2 Proof of Lemma 1.1

Consider the equation

$$(2.1) \quad x(t) - \int_0^t K(\tau, t-s)x(s)ds = f(t) \quad (t \geq 0)$$

with a fixed $\tau \geq 0$. Applying to (2.1) the Laplace transform, we have

$$\tilde{x}(z) - \tilde{K}_\tau(z)\tilde{x}(z) = \tilde{f}(z),$$

where $\tilde{x}(z)$ and $\tilde{f}(z)$ are the Laplace transforms to $x(t)$ and $f(t)$, respectively, z is the dual variable. Hence,

$$\tilde{x}(z) = W_\tau^{-1}(z)\tilde{f}(z).$$

So

$$(2.2) \quad x(t) = \int_0^t G_\tau(t-s)f(s)ds.$$

Now rewrite (1.1) in the form

$$(2.3) \quad x(t) - \int_0^t K(\tau, t-s)x(s)ds = f_0(t, \tau) + f(t) \quad (t \geq 0).$$

with

$$f_0(t, \tau) = \int_0^t (K(t, t-s) - K(\tau, t-s))x(s)ds.$$

So according to (2.2),

$$(2.4) \quad x(t) = \int_0^t G_\tau(t-s)(f(s) + f_0(s, \tau))ds = F(t) + \int_0^t G_\tau(t-s)f_0(s, \tau)ds,$$

where

$$F(t) = \int_0^t G_\tau(t-s)f(s)ds.$$

With the notation

$$w(t) := \sup_{\tau \geq 0} \|G_\tau(t)\|$$

we thus get

$$\|F\|_{C(R_+)} \leq \|f\|_{C(R_+)} \sup_t \int_0^t w(t-s)ds = \|w\|_{L^1(R_+)} \|f\|_{C(R_+)}.$$

Due to (1.3)

$$\|f_0(t, \tau)\| \leq \int_0^t \|(K(\tau, t-s) - K(t, t-s))x(s)\|ds \leq |x|_{C(0,t)}q|t - \tau|.$$

Now (2.4) implies

$$\|x(t)\| \leq \|w\|_{L^1(R_+)} \|f\|_{C(R_+)} + q \int_0^t w(t-s)|x|_{C(0,s)}|s - \tau|ds.$$

Take $t = \tau$. Then

$$\|x(\tau)\| \leq |w|_{L^1(R_+)} |f|_{C(R_+)} + q \int_0^\tau w(\tau - s) |x|_{C(0,s)} (\tau - s) ds.$$

Hence,

$$\begin{aligned} \|x(\tau)\| &\leq |w|_{L^1(R_+)} |f|_{C(R_+)} + |x|_{C(0,\tau)} \int_0^\tau (\tau - s) w(\tau - s) ds_1 \leq \\ &|w|_{L^1(R_+)} |f|_{C(R_+)} + |x|_{C(0,\tau)} \Theta, \end{aligned}$$

where

$$\Theta = q \int_0^\infty s w(s) ds.$$

Therefore, for any $t_0 > 0$,

$$\sup_{\tau \leq t_0} \|x(\tau)\| \leq |w|_{L^1(R_+)} |f|_{C(R_+)} + \sup_{\tau \leq t_0} |x|_{C(0,\tau)} \Theta.$$

Now condition (1.4) implies

$$|x|_{C(0,t_0)} \leq \frac{|w|_{L^1(R_+)} |f|_{C(R_+)}}{1 - \Theta}.$$

Since the right hand part does not depend on t_0 , inequality (1.3) follows. Besides,

$$a_0 = \frac{|w|_{L^1(R_+)}}{1 - \Theta}.$$

The existence of solutions is due to the Neumann series

$$x = \sum_{k=0}^{\infty} V^k f,$$

where V is the Volterra integral operator defined in (1.1). The lemma is proved. \square

3 The main result

First, note that

$$tG_\tau(t) = t \frac{1}{2\pi i} \int_{-i\infty}^{i\infty} e^{zt} W_\tau^{-1}(z) dz = \frac{1}{2\pi i} \int_{-i\infty}^{+i\infty} e^{zt} T(z) dz,$$

where

$$T_\tau(z) := -\frac{dW_\tau^{-1}(z)}{dz} = W_\tau^{-1}(z) \frac{dW_\tau(z)}{dz} W_\tau^{-1}(z).$$

For a number $b > 0$ and $Re z > -b$, let $T_\tau(z)$ be regular and

$$(3.1) \quad \psi_b := \sup_{\tau \geq 0} \frac{1}{2\pi} \int_{-\infty}^{\infty} \|T_\tau(iy - b)\| dy < \infty.$$

Then

$$\|tG_\tau(t)\| \leq e^{-bt} \frac{1}{2\pi} \int_{-\infty}^{\infty} \|T(iy - b)\| dy = e^{-bt} \psi_b.$$

So

$$\int_0^\infty t \sup_\tau \|G_\tau(t)\| dt \leq \psi_b \int_0^\infty e^{-bt} dt = \frac{\psi_b}{b}.$$

Now Lemma 1.1 implies our main result.

Theorem 3.1 *Under condition (1.2), for a positive b and all z with $\operatorname{Re} z > -b$, let $T_\tau(z)$ be regular, and the conditions (3.1) and $q\psi_b < b$ hold. Then Equation (1.1) is stable.*

To illustrate this result, consider in X the equation

$$(3.2) \quad x(t) - A(t) \int_0^t e^{-(t-s)h} x(s) ds = f(t) \quad (h = \text{const} > 0, t \geq 0),$$

where $A(t)$ is a variable bounded operator in X satisfying

$$(3.3) \quad \|A(t) - A(\tau)\| \leq q_1 |t - \tau| \quad (t, \tau \geq 0).$$

Take $K(t, s) = A(t)e^{-sh}$. Then

$$(3.4) \quad \int_0^t \|K(t, s) - K(\tau, s)\| ds \leq q_1 \|A(t) - A(\tau)\| \int_0^t e^{-sh} ds \leq \frac{q_1}{h} |t - \tau| \quad (t, \tau \geq 0).$$

So (1.2) holds with $q = q_1/h$. We also have

$$\tilde{K}_\tau(z) := A(\tau) \int_0^\infty e^{-zs} e^{-hs} ds = \frac{A(\tau)}{z + h}$$

and

$$W_\tau(z) := I - \frac{A(\tau)}{z + h}.$$

Hence,

$$T_\tau(z) = \left(I - \frac{A(\tau)}{z + h}\right)^{-2} \frac{A(\tau)}{(z + h)^2} = A(\tau) ((z + h)I - A(\tau))^{-2}.$$

So

$$(3.5) \quad \|T_\tau(z)\| \leq \|A(\tau)\| \|((z + h)I - A(\tau))^{-1}\|^2 \quad (\tau \geq 0).$$

Note that some estimates for resolvents of nonselfadjoint operators can be found in [10]. For instance, take $X = L^2(0, 1)$ and

$$A(t)w(y) = a(t, y) \int_0^1 m(y, y_1)w(y_1)dy_1 \quad (y \in [0, 1]),$$

where $a(t, \cdot)$ for all $t \geq 0$ is a scalar measurable function satisfying the conditions

$$\sup_{t \geq 0, y \in [0, 1]} |a(t, y)| < \infty$$

and

$$(3.6) \quad |a(t, y) - a(\tau, y)| \leq q_0 |t - \tau| \quad (y \in [0, 1]; t, \tau \geq 0).$$

In addition, the scalar function $m(., .)$ satisfies the condition

$$N_m := \left[\int_0^1 \int_0^1 |m(y, y_1)|^2 dy dy_1 \right]^{1/2} < \infty.$$

That is, we consider the equation

$$(3.7) \quad u(t, y) = f(t, y) + a(t, y) \int_0^t e^{-h(t-s)} \int_0^1 m(y, y_1) u(s, y_1) dy_1 ds \quad (0 \leq y \leq 1; t \geq 0),$$

where $f(t, .) \in L^2(0, 1)$. By the Schwarz inequality, for any $w \in L^2(0, 1)$ we get

$$\|(A(t) - A(\tau))w\|^2 = \int_0^1 |(a(t, y) - a(\tau, y)) \int_0^1 m(y, y_1) w(y_1) dy_1|^2 dy \leq (q_0 |t - \tau| N_m)^2 \|w\|^2.$$

That is, (3.3) holds with $q_1 = q_0 N_m$. So according to (3.4), condition (1.2) is valid with $q = q_0 N_m / h$. Furthermore, clearly,

$$\|A(\tau)\| \leq c(a, m) := \sup_{\tau, y} |a(\tau, y)| N_m \quad (\tau \geq 0).$$

Assume that

$$(3.8) \quad 2c(a, m) < h$$

and take $b = h/2$. Then by (3.5),

$$\|T_\tau(-b + iy)\| \leq \frac{c(a, m)}{(\sqrt{y^2 + h^2/4} - c(a, m))^2} \quad (\tau \geq 0).$$

So we have the inequality $\psi_b \leq \tilde{\psi}_h$, where

$$\tilde{\psi}_h := \frac{c(a, m)}{2\pi} \int_{-\infty}^{\infty} \frac{dy}{(\sqrt{y^2 + h^2/4} - c(a, m))^2} < \infty.$$

Thus under conditions (3.6) and (3.8), thanks to Theorem 3.1, Equation (3.7) is stable provided $2q_0 N_m \tilde{\psi}_h < h^2$.

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