

# Multiple positive solutions for second order impulsive differential equation\*

Weihua Jiang<sup>†</sup>, Qiang Zhang, Weiwei Guo

College of Sciences, Hebei University of Science and Technology

Shijiazhuang, 050018, Hebei, P. R. China

**Abstract:** We investigate the existence of positive solutions to a three-point boundary value problem of second order impulsive differential equation. Our analysis rely on the Avery-Peterson fixed point theorem in a cone. An example is given to illustrate our result.

**Keywords:** impulsive differential equation; fixed point theorem; positive solution; completely continuous operator

## 1. Introduction

Impulsive differential equations have very good applications in economics, biology, ecology and other fields(see[1-3]). Many authors are interested in the boundary value problem of impulsive differential equations (see [4-23]). For example, in [6,7], R. P. Agarwal and D. O'Regan studied the existence of solutions for the boundary value problems

$$y''(t) + \phi(t)f(t, y(t)) = 0, \quad t \in (0, 1) \setminus \{t_1, t_2, \dots, t_m\},$$

$$\Delta y(t_k) = I_k(y(t_k^-)), \quad k = 1, 2, \dots, m,$$

$$\Delta y'(t_k) = J_k(y(t_k^-)), \quad k = 1, 2, \dots, m,$$

$$y(0) = y(1) = 0,$$

by using Krasnoselskii's fixed point theorem and the Leggett Williams fixed point theorem, respectively. Using the fixed point index theory, T. Jankowski ([23]) obtained the existence of solutions for the boundary value problem

$$x''(t) + \alpha(t)f(x(\alpha(t))) = 0, \quad t \in (0, 1) \setminus \{t_1, t_2, \dots, t_m\},$$

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<sup>†</sup>Corresponding author. E-mail address: weihuajiang@hebest.edu.cn (Weihua Jiang).

$$\begin{aligned}\Delta y'(t_k) &= Q_k(x(t_k)), \quad k = 1, 2, \dots, m, \\ x(0) &= 0, \quad \beta x(\eta) = x(1).\end{aligned}$$

In paper [26], quite general impulsive boundary value problems

$$\begin{aligned}u''(t) + p(t)u'(t) + q(t)u(t) + g(t)f(t, u(t)) &= 0, \quad t \in (0, 1), \quad t \neq \tau, \\ \Delta u_{(t=\tau)} &= I(u(\tau)), \\ \Delta u'_{(t=\tau)} &= N(u(\tau)), \\ a_1 u(0) - b_1 u'(0) &= \alpha[u], \quad a_2 u(1) - b_2 u'(1) = \beta[u].\end{aligned}$$

are treated.

Motivated by the excellent results mentioned above and the methods used in [24], in this paper, we examine the second order impulsive equation

$$\begin{cases} u''(t) + \phi(t)f(t, u(t)) = 0, & t \in (0, 1) \setminus \{t_1, t_2, \dots, t_m\}, \\ \Delta u(t_k) = I_k(u(t_k)), & k = 1, 2, \dots, m, \\ \Delta u'(t_k) = J_k(u(t_k)), & k = 1, 2, \dots, m, \\ u(0) = \alpha u(\xi), \quad u'(1) = 0, \end{cases} \quad (1.1)$$

where  $\alpha, \xi \in (0, 1)$ ,  $0 < t_1 < t_2 < \dots < t_m < 1$ ,  $\xi \neq t_k$ ,  $k = 1, 2, \dots, m$ ,  $\Delta u(t_k) = u(t_k^+) - u(t_k^-)$ ,  $u(t_k^+)$  (respectively  $u(t_k^-)$ ) denotes the right limit (respectively left limit) of  $u(t)$  at  $t = t_k$ . Also  $\Delta u'(t_k) = u'(t_k^+) - u'(t_k^-)$ . Our result complements the results of [6,7,23] and it can solve the problems which cannot be solved by the results of [26](see example 3.1).

We define the Banach space:

$$\begin{aligned}PC[0, 1] &= \{u : [0, 1] \rightarrow R, \text{ there exists } u_k \in C[t_k, t_{k+1}] \text{ such that } u(t) = u_k(t) \\ &\text{for } t \in (t_k, t_{k+1}], \quad k = 0, 1, \dots, m, \quad u(0) = u(0+0)\},\end{aligned}$$

with the norm

$$\|u\| = \sup\{|u(t)| : t \in [0, 1] \setminus \{t_1, \dots, t_m\}\},$$

where  $t_0 = 0$ ,  $t_{m+1} = 1$ .

A positive solution of the problem (1.1) means a function  $u \in PC[0, 1]$  which satisfies (1.1) with  $u(t) > 0$ ,  $t \in [0, 1]$ .

In this paper, we will always suppose that the following conditions hold:

- (C<sub>1</sub>)  $\phi \in C(0, 1)$  with  $\phi > 0$  on  $(0, 1)$  and  $\phi \in L^1[0, 1]$ .
- (C<sub>2</sub>)  $f : [0, 1] \times [0, \infty) \rightarrow [0, \infty)$  is continuous.
- (C<sub>3</sub>)  $I_k, J_k : [0, \infty) \rightarrow R$  are continuous for  $k = 1, 2, \dots, m$ .

(C<sub>4</sub>) There exists a function  $\Omega : \{u : u \in PC[0, 1], u \geq 0\} \rightarrow [0, +\infty)$  and a constant  $0 < c_0 < 1$  such that

$$c_0\Omega(u) \leq \omega_0(t, u) \leq \Omega(u), \quad (t, u) \in [0, 1] \times \{u : u \in PC[0, 1], u \geq 0\},$$

where

$$\begin{aligned} \omega_0(t, u) = & \frac{\alpha}{1-\alpha} \sum_{t_k < \xi} [I_k(u(t_k)) + (\xi - t_k)J_k(u(t_k))] \\ & + \sum_{t_k < t} \left[ I_k(u(t_k)) - \frac{\alpha\xi + (1-\alpha)t_k}{1-\alpha} J_k(u(t_k)) \right] - \sum_{t \leq t_k} \frac{\alpha\xi + (1-\alpha)t}{1-\alpha} J_k(u(t_k)). \end{aligned}$$

## 2. Preliminaries

For  $y \in L[0, 1]$ , let's consider the following problem:

$$\begin{cases} u''(t) + y(t) = 0, & t \in (0, 1) \setminus \{t_1, t_2, \dots, t_m\}, \\ \Delta u(t_k) = I_k(u(t_k)), & k = 1, 2, \dots, m, \\ \Delta u'(t_k) = J_k(u(t_k)), & k = 1, 2, \dots, m, \\ u(0) = \alpha u(\xi), \quad u'(1) = 0. \end{cases} \quad (2.1)$$

**Lemma 2.1** Let  $u \geq 0$ . Then  $u$  is a solution of the problem (2.1) if and only if it satisfies

$$u(t) = \int_0^1 G(t, s)y(s)ds + \omega_0(t, u), \quad (2.2)$$

where

$$G(t, s) = \frac{1}{1-\alpha} \begin{cases} s, & s < \xi, s < t, \\ \alpha s + (1-\alpha)t, & t \leq s \leq \xi, \\ \alpha\xi + (1-\alpha)s, & \xi \leq s \leq t, \\ \alpha\xi + (1-\alpha)t, & \xi < s, t < s, \end{cases}$$

$\omega_0(t, u)$  is the same as in condition (C<sub>4</sub>).

**Proof.** Let  $u$  be a solution of the problem (2.1), then

$$u''(t) = -y(t). \quad (2.3)$$

For  $t \in (0, t_1]$ , integrating (2.3) from 0 to  $t$ , we have

$$\begin{aligned} u'(t) &= c_1 - \int_0^t y(s)ds, \\ u(t) &= c_2 + c_1t - \int_0^t (t-s)y(s)ds. \end{aligned}$$

So, we have

$$u(t_1^-) = c_1t_1 - \int_0^{t_1} (t_1-s)y(s)ds + c_2, \quad (2.4)$$

$$u'(t_1^-) = c_1 - \int_0^{t_1} y(s)ds. \quad (2.5)$$

For  $t \in (t_1, t_2]$ , integrating (2.3) from  $t_1$  to  $t$ , we have

$$u(t) = b_2 + b_1(t - t_1) - \int_{t_1}^t (t - s)y(s)ds. \quad (2.6)$$

By (2.1), (2.4), (2.5) and (2.6), we have

$$b_2 = I_1(u(t_1)) + c_1 t_1 - \int_0^{t_1} (t_1 - s)y(s)ds + c_2,$$

$$b_1 = J_1(u(t_1)) + c_1 - \int_0^{t_1} y(s)ds.$$

Thus,

$$u(t) = I_1(u(t_1)) + c_1 t - \int_0^t (t - s)y(s)ds + J_1(u(t_1))(t - t_1) + c_2.$$

For  $t \in (t_k, t_{k+1}]$ , by the same way, we can get

$$u(t) = c_1 t + c_2 - \int_0^t (t - s)y(s)ds + \sum_{i=1}^k (t - t_i)J_i(u(t_i)) + \sum_{i=1}^k I_i(u(t_i)). \quad (2.7)$$

By  $u'(1) = 0$  and (2.7), we have

$$c_1 = \int_0^1 y(s)ds - \sum_{i=1}^m J_i(u(t_i)).$$

It follows from (2.7) and  $u(0) = \alpha u(\xi)$  that

$$c_2 = \frac{\alpha}{1 - \alpha} \left[ \xi \int_0^1 y(s)ds - \int_0^\xi (\xi - s)y(s)ds - \sum_{k=1}^m \xi J_k(u(t_k)) + \sum_{t_k < \xi} (\xi - t_k)J_k(u(t_k)) + \sum_{t_k < \xi} I_k(u(t_k)) \right].$$

So, we get

$$\begin{aligned} u(t) &= \int_0^1 ty(s)ds + \frac{\alpha\xi}{1 - \alpha} \int_0^1 y(s)ds - \frac{\alpha}{1 - \alpha} \int_0^\xi (\xi - s)y(s)ds - \int_0^t (t - s)y(s)ds \\ &+ \frac{\alpha}{1 - \alpha} \sum_{t_k < \xi} [I_k(u(t_k)) + (\xi - t_k)J_k(u(t_k))] + \sum_{t_k < t} \left[ I_k(u(t_k)) - \frac{\alpha\xi + (1 - \alpha)t_k}{1 - \alpha} J_k(u(t_k)) \right] \\ &- \sum_{t \leq t_k} \frac{\alpha\xi + (1 - \alpha)t}{1 - \alpha} J_k(u(t_k)) \\ &= \int_0^1 ty(s)ds + \frac{\alpha\xi}{1 - \alpha} \int_0^1 y(s)ds - \frac{\alpha}{1 - \alpha} \int_0^\xi (\xi - s)y(s)ds - \int_0^t (t - s)y(s)ds + \omega_0(t, u). \end{aligned}$$

For  $t \leq \xi$ , we obtain

$$u(t) = \int_0^t \frac{s}{1 - \alpha} y(s)ds + \int_t^\xi \frac{\alpha s + (1 - \alpha)t}{1 - \alpha} y(s)ds + \int_\xi^1 \frac{\alpha\xi + (1 - \alpha)t}{1 - \alpha} y(s)ds + \omega_0(t, u).$$

For  $t \geq \xi$ , we have

$$u(t) = \int_0^\xi \frac{s}{1-\alpha} y(s) ds + \int_\xi^t \frac{\alpha\xi + (1-\alpha)s}{1-\alpha} y(s) ds + \int_t^1 \frac{\alpha\xi + (1-\alpha)t}{1-\alpha} y(s) ds + \omega_0(t, u).$$

So, we get

$$u(t) = \int_0^1 G(t, s) y(s) ds + \omega_0(t, u).$$

Conversely, if  $u(t)$  satisfies (2.2), it's easy to get that  $u(t)$  is a solution of (2.1).  $\square$

**Lemma 2.2.** The function  $G(t, s)$  is continuous on  $[0, 1] \times [0, 1]$  and it satisfies

$$\rho_0 g(s) \leq G(t, s) \leq g(s), \quad t, s \in [0, 1],$$

where  $g(s) = \frac{s}{1-\alpha}$ ,  $\rho_0 = \alpha\xi$ .

**Proof.** The proof of this lemma is easy. So, we omit it.  $\square$

Now we define a cone  $P$  on  $PC[0, 1]$  and an operator  $T : P \rightarrow PC[0, 1]$  as follows:

$$P = \{u \in PC[0, 1] : u(t) \geq 0, \inf_{t \in [0, 1]} u(t) \geq \rho \|u\|\}, \quad \text{where } \rho = \min\{c_0, \rho_0\}.$$

$$Tu(t) = \int_0^1 G(t, s) \phi(s) f(s, u(s)) ds + \omega_0(t, u).$$

Obviously, if  $u \in P$  is a fixed point of  $T$ , it is a solution of the problem (1.1).

**Lemma 2.3.** Assume  $(C_1) - (C_4)$  hold. Then  $T : P \rightarrow P$  is a completely continuous operator.

**Proof.** By  $(C_1)$ ,  $(C_2)$  and  $(C_4)$ , we have  $Tu(t) \geq 0$ ,  $u \in P$ . By  $(C_4)$  and Lemma 2.2, we can get

$$\begin{aligned} |Tu(t)| &= \left| \int_0^1 G(t, s) \phi(s) f(s, u(s)) ds + \omega_0(t, u) \right| \\ &\leq \int_0^1 g(s) \phi(s) f(s, u(s)) ds + \Omega(u), \end{aligned}$$

and

$$\begin{aligned} \inf_{t \in [0, 1]} Tu(t) &= \inf_{t \in [0, 1]} \left[ \int_0^1 G(t, s) \phi(s) f(s, u(s)) ds + \omega_0(t, u) \right] \\ &\geq \rho_0 \int_0^1 g(s) \phi(s) f(s, u(s)) ds + c_0 \Omega(u) \\ &\geq \rho \|Tu\|. \end{aligned}$$

This shows that  $T : P \rightarrow P$ . By the continuity of  $f$ ,  $I_k$ ,  $J_k$ ,  $k = 1, 2, \dots, m$ , we can easily obtain that  $T : P \rightarrow P$  is continuous. Let  $S \subset P$  be bounded. Obviously,  $T(S) \subset P$  is bounded. For  $u \in S$ ,  $t, t' \in (t_k, t_{k+1}]$ , we have

$$\begin{aligned} |Tu(t) - Tu(t')| &\leq \int_0^1 |G(t, s) - G(t', s)| \phi(s) f(s, u(s)) ds + |\omega_0(t, u) - \omega_0(t', u)| \\ &\leq \int_0^1 |G(t, s) - G(t', s)| \phi(s) f(s, u(s)) ds + |t - t'| \sum_{k=1}^m |J_k(u(t_k))|. \end{aligned}$$

By  $(C_1)$ , the uniform continuity of  $G$  on  $[0, 1] \times [0, 1]$ , the boundedness of  $f$  on  $[0, 1] \times S$  and the boundedness of  $J_k$  on  $S$ , we obtain that  $T(S)$  is quasi-equicontinuous on  $[0, 1]$ . By [1],  $T$  is a compact map. So,  $T : P \rightarrow P$  is completely continuous.  $\square$

In order to obtain our main results, we need the following definitions and theorem.

**Definition 2.1.** A map  $\phi$  is said to be a non-negative, continuous and concave functional on a cone  $P$  of a real Banach space  $E$  iff  $\phi : P \rightarrow R_+$  is continuous and

$$\phi(tx + (1 - t)y) \geq t\phi(x) + (1 - t)\phi(y),$$

for all  $x, y \in P$  and  $t \in [0, 1]$ .

**Definition 2.2.** A map  $\Phi$  is said to be a non-negative, continuous and convex functional on a cone  $P$  of a real Banach space  $E$  iff  $\Phi : P \rightarrow R_+$  is continuous and

$$\Phi(tx + (1 - t)y) \leq t\Phi(x) + (1 - t)\Phi(y),$$

for all  $x, y \in P$  and  $t \in [0, 1]$ .

Let  $\varphi$  and  $\Theta$  be non-negative, continuous and convex functional on  $P$ ,  $\Phi$  be a non-negative, continuous and concave functional on  $P$ , and  $\Psi$  be a non-negative continuous functional on  $P$ . Then, for positive numbers  $a, b, c$  and  $d$ , we define the following sets:

$$P(\varphi, d) = \{x \in P : \varphi(x) < d\},$$

$$P(\varphi, \Phi, b, d) = \{x \in P : b \leq \Phi(x), \varphi(x) \leq d\},$$

$$P(\varphi, \Theta, \Phi, b, c, d) = \{x \in P : b \leq \Phi(x), \Theta(x) \leq c, \varphi(x) \leq d\},$$

$$R(\varphi, \Psi, a, d) = \{x \in P : a \leq \Psi(x), \varphi(x) \leq d\}.$$

We will use the following fixed point theorem of Avery and Peterson to study the problem (1.1), (2.1).

**Theorem 2.1[25].** Let  $P$  be a cone in a real Banach space  $E$ . Let  $\varphi$  and  $\Theta$  be non-negative, continuous and convex functionals on  $P$ ,  $\Phi$  be a non-negative, continuous and concave functional on  $P$ , and  $\Psi$  be a non-negative continuous functional on  $P$  satisfying  $\Psi(kx) \leq k\Psi(x)$  for  $0 \leq k \leq 1$ , such that for some positive numbers  $M$  and  $d$ ,

$$\Phi(x) \leq \Psi(x) \text{ and } \|x\| \leq M\varphi(x)$$

for all  $x \in \overline{P(\varphi, d)}$ . Suppose that

$$T : \overline{P(\varphi, d)} \rightarrow \overline{P(\varphi, d)}$$

is completely continuous and there exist positive numbers  $a, b, c$  with  $a < b$ , such that the following conditions are satisfied:

- (S<sub>1</sub>)  $\{x \in P(\varphi, \Theta, \Phi, b, c, d) : \Phi(x) > b\} \neq \emptyset$  and  $\Phi(Tx) > b$  for  $x \in P(\varphi, \Theta, \Phi, b, c, d)$ ;  
(S<sub>2</sub>)  $\Phi(Tx) > b$  for  $x \in P(\varphi, \Phi, b, d)$  with  $\Theta(Tx) > c$ ;  
(S<sub>3</sub>)  $0 \notin R(\varphi, \Psi, a, d)$  and  $\Psi(Tx) < a$  for  $x \in R(\varphi, \Psi, a, d)$  with  $\Psi(x) = a$ .

Then  $T$  has at least three fixed points  $x_1, x_2, x_3 \in \overline{P(\varphi, d)}$ , such that

$$\varphi(x_i) \leq d, \text{ for } i = 1, 2, 3,$$

and

$$b < \Phi(x_1), \quad a < \Psi(x_2), \quad \Phi(x_2) < b, \\ \Psi(x_3) < a.$$

### 3. Main results

We define a concave function  $\Phi(x) = \inf_{t \in [0,1]} |x(t)|$  and convex functions  $\Psi(x) = \Theta(x) = \varphi(x) = \|x\|$ .

**Theorem 3.1.** Suppose (C<sub>1</sub>) – (C<sub>4</sub>) hold. In additions, we assume that there exist positive constants  $\mu, L, a, b, c, d$  with  $a < b < \frac{b}{\rho} = c < d, \mu > D_1 + D_2, 0 < L < \rho(D_1 + D_3)$ , where  $D_1 = \int_0^1 g(s)\phi(s)ds, D_2, D_3 \geq 0$ , such that the following conditions hold:

- (A<sub>1</sub>)  $f(t, u) \leq \frac{d}{\mu}$ , for  $(t, u) \in [0, 1] \times [0, d]$ , and  $\omega_0(t, u) \leq \frac{D_2}{\mu}d$ , for  $u \in P, \|u\| \leq d$ ;  
(A<sub>2</sub>)  $f(t, u) \geq \frac{b}{L}$ , for  $(t, u) \in [0, 1] \times \left[b, \frac{b}{\rho}\right]$ , and  $\omega_0(t, u) \geq \frac{D_3}{L}b$ , for  $u \in P, b \leq u(t) \leq \frac{b}{\rho}, t \in [0, 1]$ ;

- (A<sub>3</sub>)  $f(t, u) \leq \frac{a}{\mu}$ , for  $(t, u) \in [0, 1] \times [0, a]$ , and  $\omega_0(t, u) \leq \frac{D_2}{\mu}a$ , for  $u \in P, \|u\| \leq a$ .

Then the problem (1.1) has at least two positive solutions when  $f(t, 0) \equiv 0, t \in [0, 1]$  and at least three positive solutions when  $f(t, 0) \not\equiv 0, t \in [0, 1]$ .

**Proof.** Take  $u \in \overline{P(\varphi, d)}$ . By assumption (A<sub>1</sub>), we have

$$\begin{aligned} \varphi(Tu) = \|Tu\| &\leq \int_0^1 g(s)\phi(s)f(s, u(s))ds + \frac{D_2}{\mu}d \\ &\leq \frac{d}{\mu} \int_0^1 g(s)\phi(s)ds + \frac{D_2}{\mu}d = \frac{D_1}{\mu}d + \frac{D_2}{\mu}d < d. \end{aligned}$$

Thus,  $T : \overline{P(\varphi, d)} \rightarrow \overline{P(\varphi, d)}$ .

Let's prove that condition S<sub>1</sub> holds.

Take  $u(t) = \frac{b(\rho + 1)}{2\rho}, t \in [0, 1]$ . By simple calculation, we can get that

$$\|u\| = \frac{b(\rho + 1)}{2\rho} < \frac{b}{\rho} = c,$$

and

$$\Phi(u) = \inf_{t \in [0,1]} |u(t)| = \frac{b(\rho + 1)}{2\rho} > b.$$

Therefore,

$$\{u \in P(\varphi, \Theta, \Phi, b, c, d) : b < \Phi(u)\} \neq \emptyset.$$

$u \in P(\varphi, \Theta, \Phi, b, c, d)$  means that  $b \leq u(t) \leq \frac{b}{\rho}$ ,  $t \in [0, 1]$ . By  $(A_2)$ , we get

$$\Phi(Tu) = \inf_{t \in [0,1]} |Tu(t)| \geq \rho \left[ \int_0^1 g(s)\phi(s)f(s, u(s))ds + \frac{b}{L}D_3 \right] \geq \rho \frac{b}{L}(D_1 + D_3) > b.$$

So, condition  $S_1$  holds.

Now we will show that condition  $S_2$  holds.

Take  $u \in P(\varphi, \Phi, b, d)$  and  $\|Tu\| > \frac{b}{\rho} = c$ . Considering  $Tu \in P$ , we get

$$\Phi(Tu) = \inf_{t \in [0,1]} |Tu(t)| \geq \rho \|Tu\| > \rho \cdot \frac{b}{\rho} = b,$$

This shows that condition  $S_2$  is satisfied.

In the following we will show that the condition  $S_3$  is satisfied. Since  $\Psi(0) = 0$ ,  $0 < a$ ,  $0 \notin R(\varphi, \Psi, a, d)$ . Assume that  $u \in R(\varphi, \Psi, a, d)$  with  $\Psi(u) = \|u\| = a$ . Then, by  $(A_3)$ , we have

$$\Psi(Tu) = \|Tu(t)\| \leq \int_0^1 g(s)\phi(s)f(s, u(s))ds + \frac{a}{\mu}D_2 \leq \frac{a}{\mu}(D_1 + D_2) < a.$$

Thus, condition  $S_3$  is satisfied. By Theorem 2.1, we get that the problem (1.1) has at least three solutions  $u_1, u_2, u_3 \in P$  satisfying

$$\|u_i\| \leq d, \quad i = 1, 2, 3, \quad \text{and} \quad b < \inf_{t \in [0,1]} |u_1(t)|,$$

$$a \leq \|u_2\|, \quad \inf_{t \in [0,1]} |u_2(t)| < b, \quad \|u_3\| < a.$$

Obviously,  $u_1(t) > 0$ ,  $u_2(t) > 0$ ,  $t \in [0, 1]$ . If  $f(t, 0) \neq 0$ ,  $t \in [0, 1]$ , then  $u = 0$  is not a solution of (1.1). So,  $u_3 \neq 0$ . This, together with  $u_3 \in P$ , means that  $u_3(t) > 0$ ,  $t \in [0, 1]$ .  $\square$

**Example 3.1.** Consider the following boundary value problem

$$\begin{cases} u''(t) + f(t, u(t)) = 0, & t \in (0, 1) \setminus \{\frac{1}{8}\}, \\ \Delta u(\frac{1}{8}) = I_1(u(\frac{1}{8})), \\ \Delta u'(\frac{1}{8}) = J_1(u(\frac{1}{8})), \\ u(0) = \frac{1}{4}u(\frac{1}{4}), \quad u'(1) = 0, \end{cases} \quad (3.1)$$



where

$$f(t, u) = \begin{cases} \frac{1}{4}u^2t, & t \in [0, 1], u \in [0, \frac{1}{2}], \\ \frac{1}{2}u^2t(1-u) + (60 + 2\sqrt{ut})(u - \frac{1}{2}), & t \in [0, 1], u \in [\frac{1}{2}, 1], \\ 30 + \sqrt{ut}, & t \in [0, 1], u \in [1, 16], \\ 30 + 4t, & t \in [0, 1], u \in [16, \infty). \end{cases}$$

Corresponding to Theorem 3.1, we take  $\alpha = \xi = \frac{1}{4}, c_0 = \frac{1}{6}, \rho = \frac{1}{16}, \mu = 2, D_1 = \int_0^1 g(s)ds = \frac{2}{3}, D_2 = \frac{1}{3}, D_3 = 0, L = \frac{1}{30}, I_1(\omega) = \frac{1}{64}\sqrt{\omega}, J_1(\omega) = \frac{-\sqrt{\omega}}{64}, \Omega(u) = \frac{3\sqrt{u(\frac{1}{8})}}{128}$ , and

$$\omega_0(t, u) = \begin{cases} \frac{3\sqrt{u(\frac{1}{8})}}{128}, & t > \frac{1}{8}, \\ (\frac{3}{8} + t)\frac{1}{64}\sqrt{u(\frac{1}{8})}, & t \leq \frac{1}{8}. \end{cases}$$

It is easy to check that  $\frac{1}{6}\Omega(u) \leq \omega_0(t, u) \leq \Omega(u)$ . Let  $a = \frac{1}{2}, b = 1, d = 68$ . By simple calculation, we can get that the conditions of Theorem 3.1 are satisfied. So, the problem (3.1) has at least three solutions  $u_1, u_2, u_3 \in P$  satisfying

$$\|u_i\| \leq 68, \quad i = 1, 2, 3,$$

and

$$1 < \Phi(u_1), \quad \frac{1}{2} < \|u_2\|, \quad \Phi(u_2) < 1, \quad \|u_3\| < \frac{1}{2},$$

where  $u_1, u_2$  are positive solutions of (3.1).

**Remark.** Corresponding to the condition  $(C_3)$  in [26], we get  $(d_1I + e_1N)(\omega) = \frac{9}{512}\sqrt{\omega}, (d_2I + e_2N)(\omega) = \frac{1}{64}\sqrt{\omega}$ . The problem (3.1) cannot be solved by the Theorems in [26] because the condition  $(C_3)$  in [26] is not satisfied. So, our result may be considered as a complementary result of [26].

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